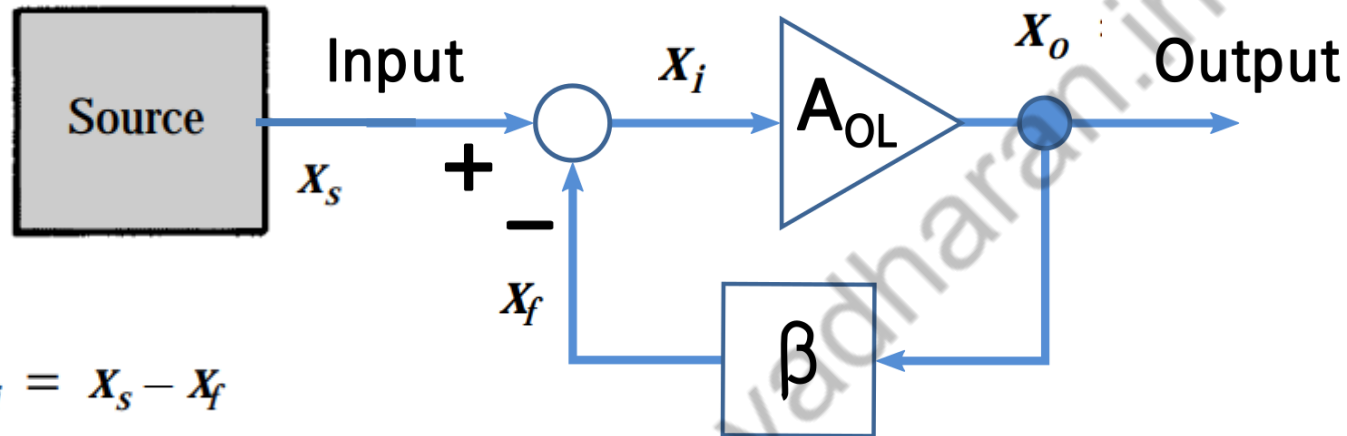




Analog IC Design : 2022-23
Lecture 10
Feedback
By Dr. Sanjay Vidhyadharan

sanjayvidhyadharan.in

Negative Feedback



$$x_i = x_s - x_f$$

$$x_f = \beta x_o$$

$$x_o = A x_i$$

$$x_o = A x_s - A x_f$$

$$x_o = A x_s - A \beta x_o$$

$$x_o = \frac{A x_s}{1 + A \beta}$$

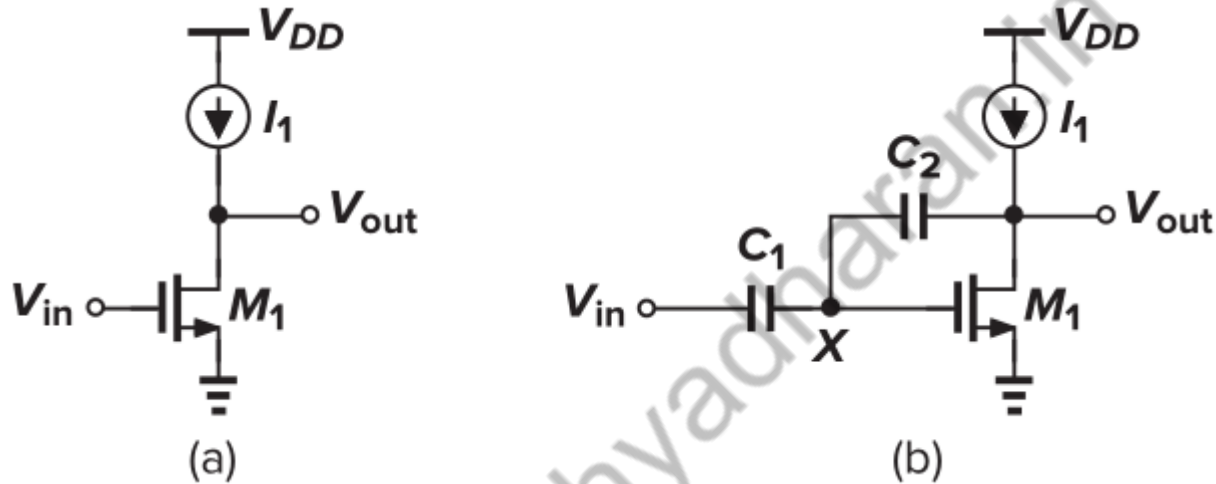
$$\text{Closed loop gain } A_f = \frac{x_o}{x_s} = \frac{A}{1 + A \beta}$$

$A \beta$ is called the **loop gain** and is generally $\gg 1$

$$A_f \approx \frac{1}{\beta}$$

The feedback network usually consists of passive components, which are accurate, and hence the overall gain will have very little dependence on the gain of the basic amplifier, A , a desirable property because the gain A is usually a function of many manufacturing and application parameters, some of which might have wide tolerances.

Gain Desensitization



(a) Simple common-source stage; (b) circuit of (a) with feedback.

$$V_{out}/V_X = -g_{m1}r_{O1}$$

$$(V_{out} - V_X)C_2s = (V_X - V_{in})C_1s$$

$$\frac{V_{out}}{V_{in}} = -\frac{1}{\left(1 + \frac{1}{g_{m1}r_{O1}}\right) \frac{C_2}{C_1} + \frac{1}{g_{m1}r_{O1}}}$$

$$\frac{V_{out}}{V_{in}} = -\frac{C_1}{C_2}$$

Advantages of Negative Feedback

Gain Desensitivity

$$A_f = \frac{A}{1 + A\beta}$$

$$dA_f = \frac{(1 + A\beta)dA - A\beta dA}{(1 + A\beta)^2}$$

$$dA_f = \frac{dA}{(1 + A\beta)^2}$$

$$\frac{dA_f}{A_f} = \frac{dA}{(1 + A\beta)A}$$

Bandwidth Extension

$$A(s) = \frac{A_M}{1 + s/\omega_H}$$

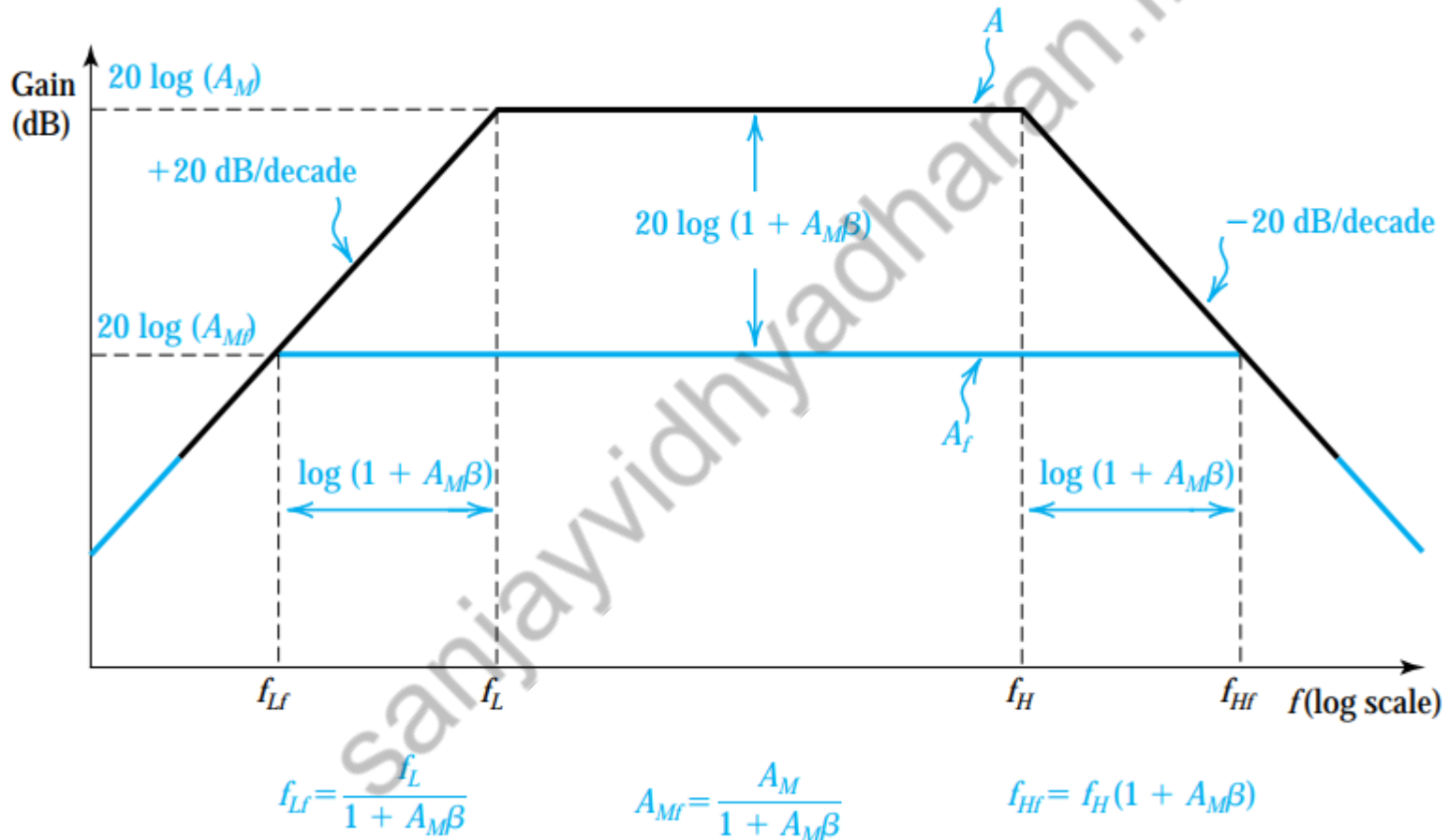
$$A_f(s) = \frac{A(s)}{1 + \beta A(s)}$$

$$A_f(s) = \frac{\frac{A_M}{1 + s/\omega_H}}{1 + \frac{\beta A_M}{1 + s/\omega_H}}$$

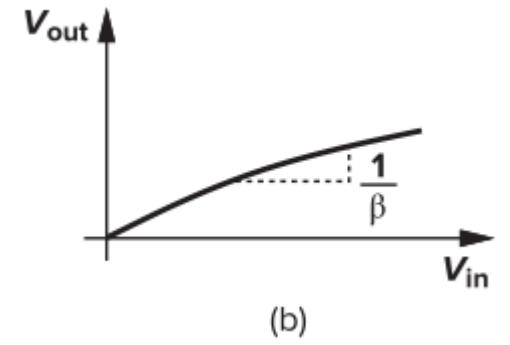
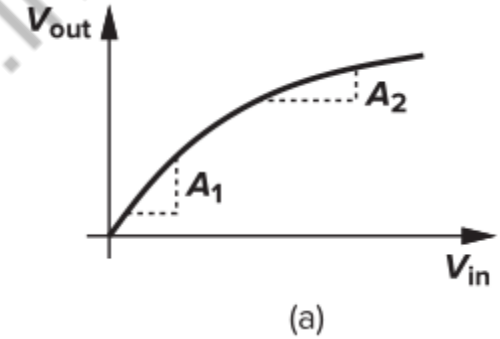
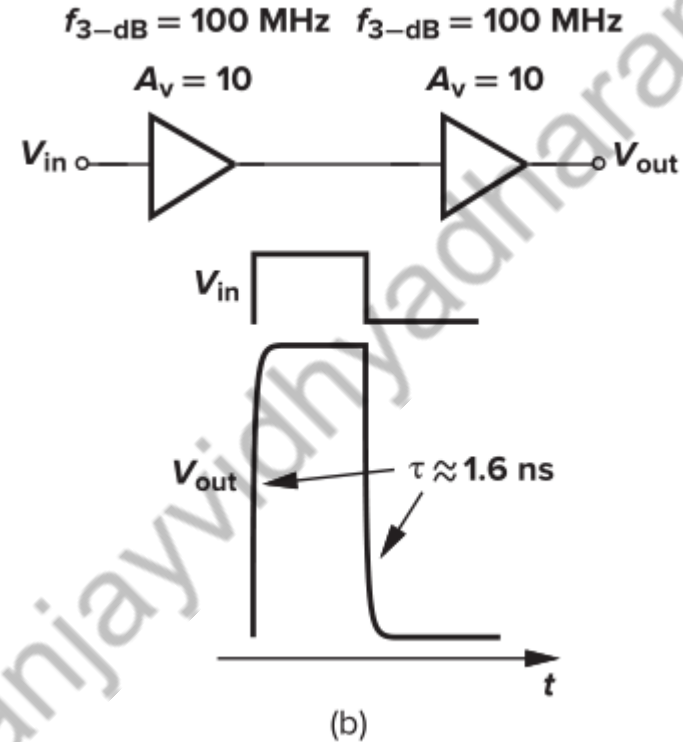
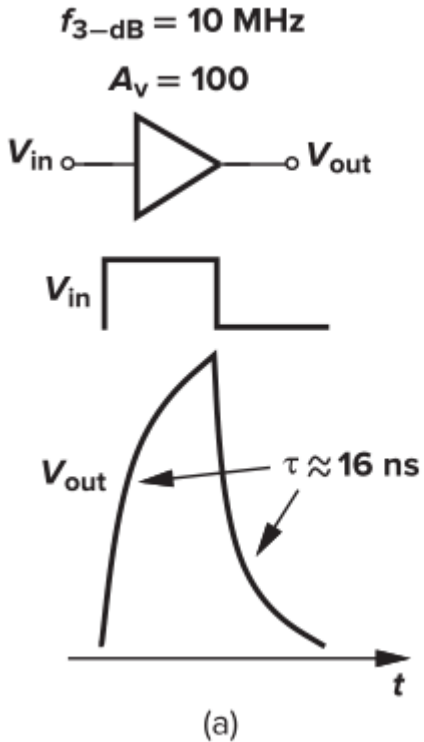
$$A_f(s) = \frac{A_M}{1 + \beta A_M + s/\omega_H}$$

$$A_f(s) = \frac{A_M/(1 + A_M\beta)}{1 + s/\omega_H(1 + A_M\beta)}$$

Advantages of Negative Feedback



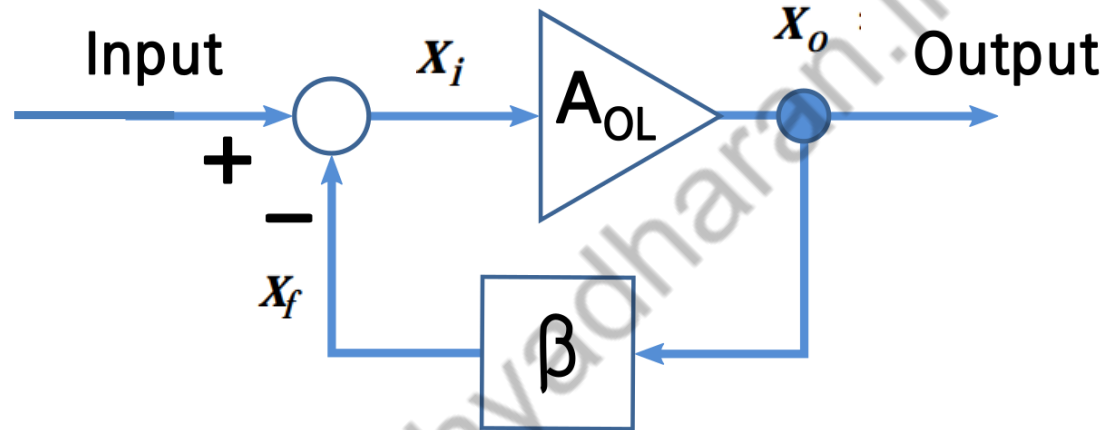
Advantages of Negative Feedback



Amplification of a 20-MHz square wave by (a) a 10-MHz amplifier and (b) a cascade of two 100-MHz feedback amplifiers.

Advantages of Negative Feedback

Noise Reduction



With Feedback

Without Feedback

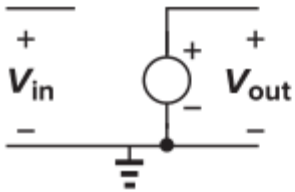
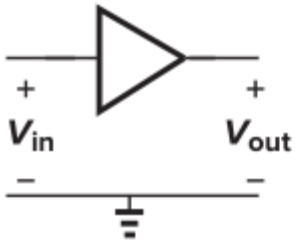
$$N_{out} = AN_{in} + N_{amp}$$

$$N_{out_f} = A(N_{in} - \beta N_{out_f}) + N_{amp}$$

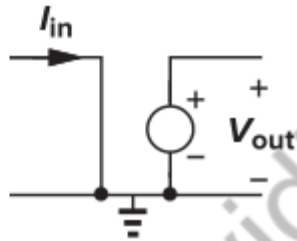
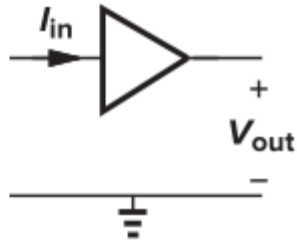
$$N_{out_f} = \frac{AN_{in}}{1 + A\beta} + \frac{N_{amp}}{1 + A\beta}$$

Types of Amplifiers

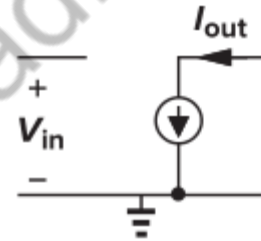
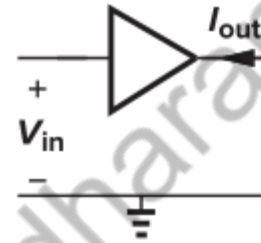
Voltage Amp.



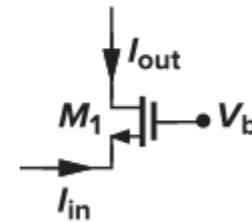
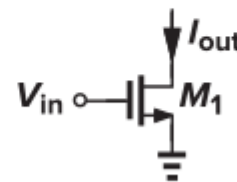
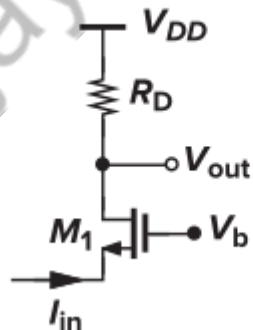
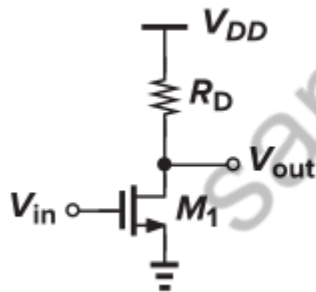
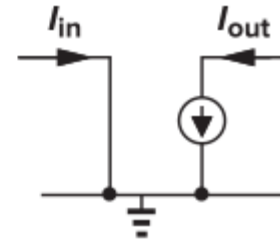
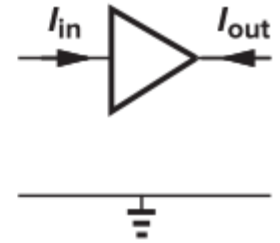
Transimpedance Amp.



Transconductance Amp.

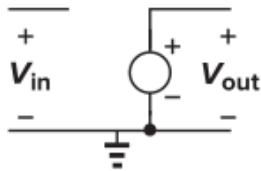
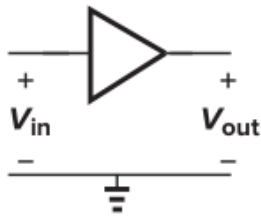


Current Amp.

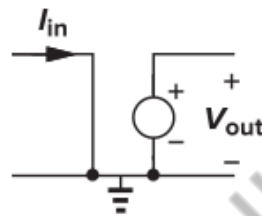
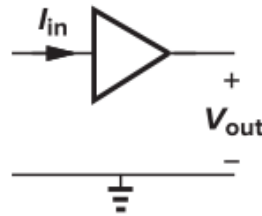


Types of Amplifiers

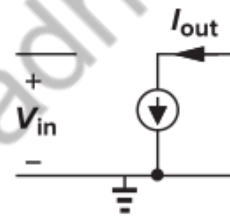
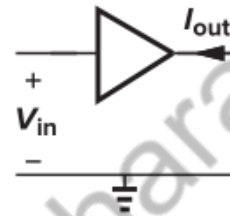
Voltage Amp.



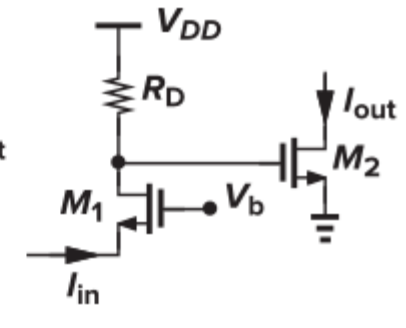
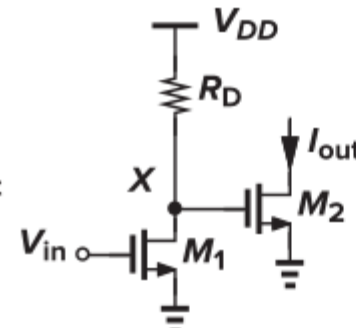
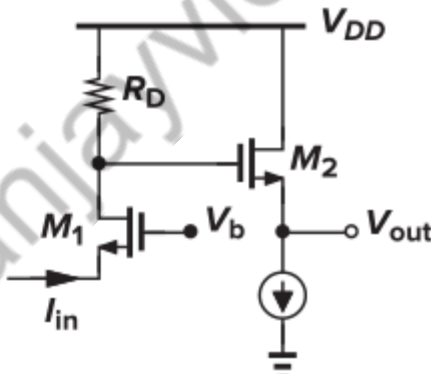
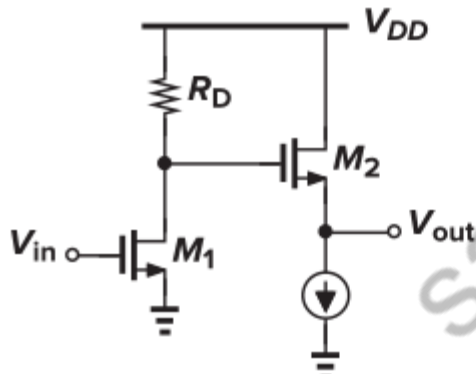
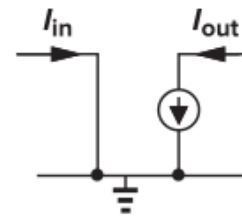
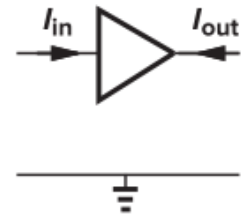
Transimpedance Amp.



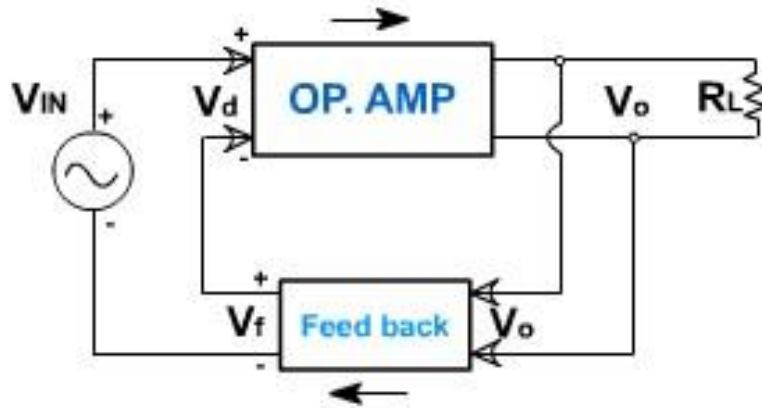
Transconductance Amp.



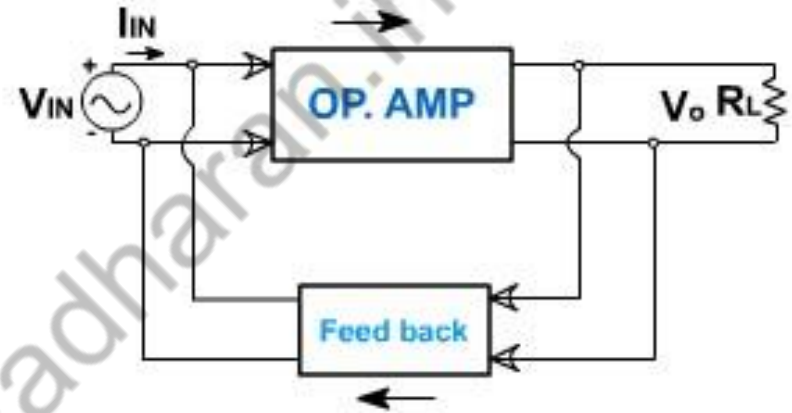
Current Amp.



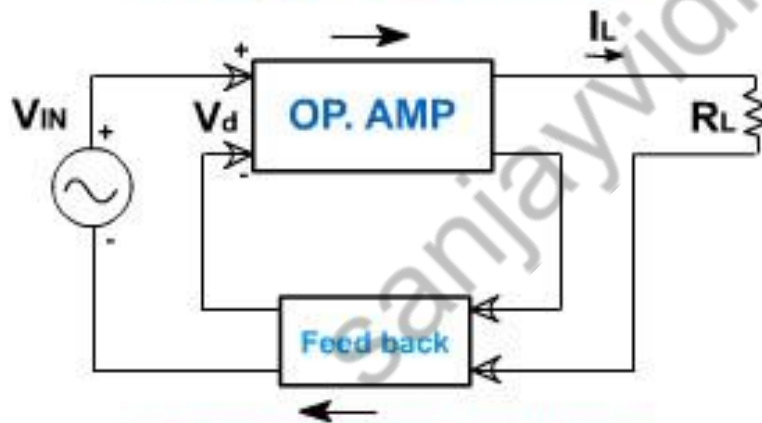
Basic Feedback Topologies



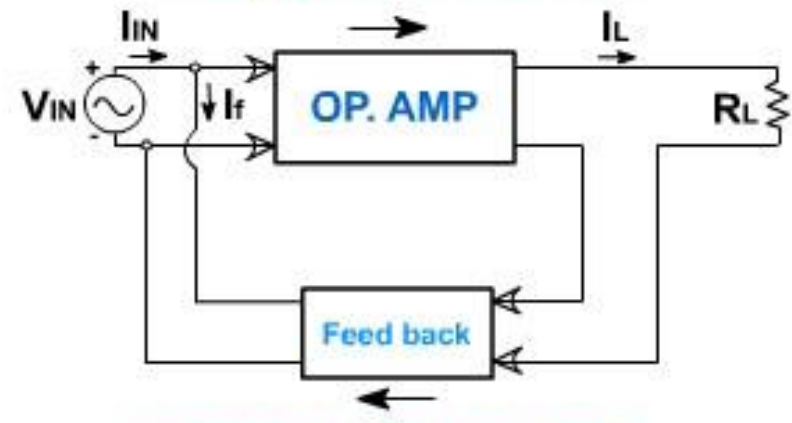
Voltage series feedback



Voltage shunt feedback



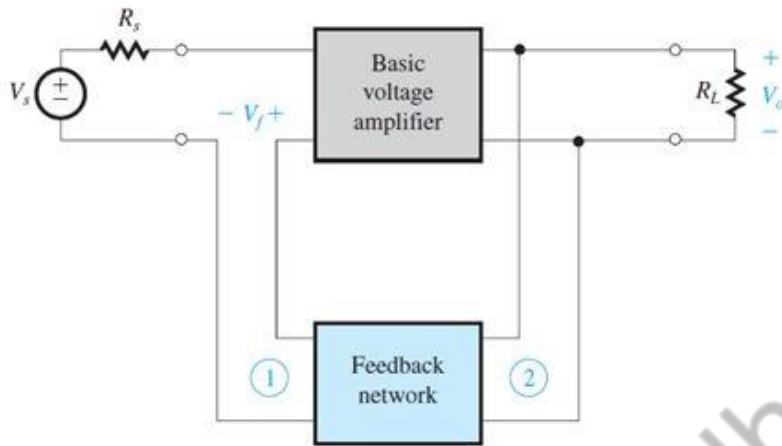
Current series feedback



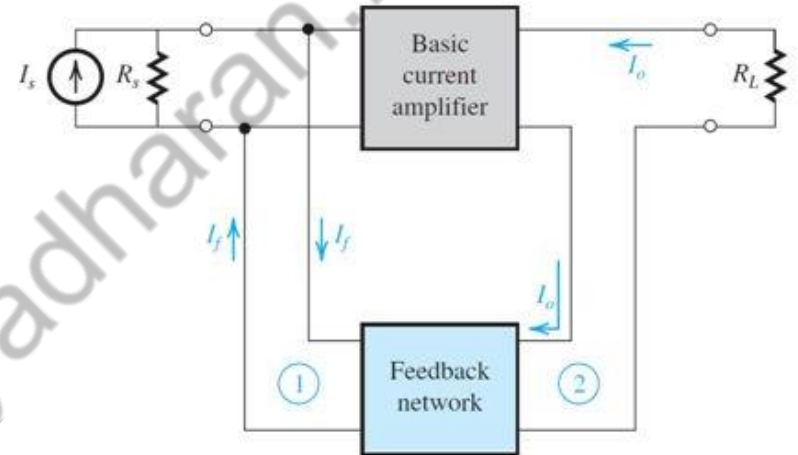
Current shunt feedback

Basic Feedback Topologies

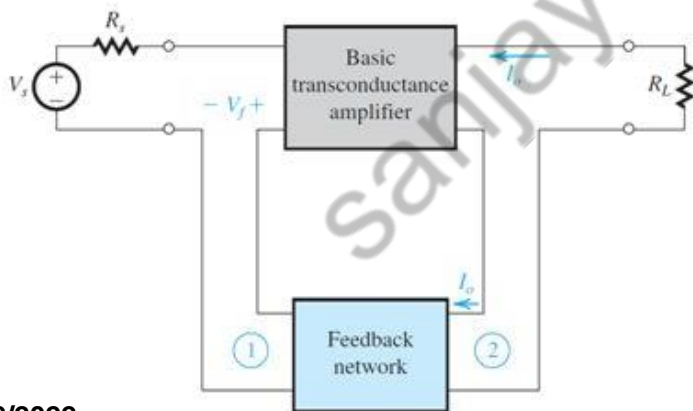
(a) Voltage amplifiers (series–shunt feedback)



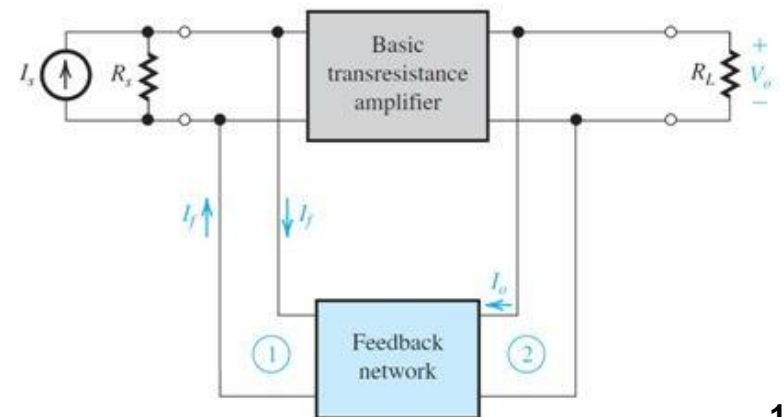
(b) Current amplifiers (shunt–series feedback)



(c) Trans-conductance amplifiers (series–series feedback)



(d) Trans-resistance amplifiers (shunt–shunt)



Series-Shunt Feedback Amplifier (Voltage-Voltage Feedback)

$$V_f = \beta V_o$$

$$V_i = V_s - V_f$$

$$V_o = A(V_s - \beta V_o)$$

$$A_f \equiv \frac{V_o}{V_s} = \frac{A}{1 + \beta A}$$

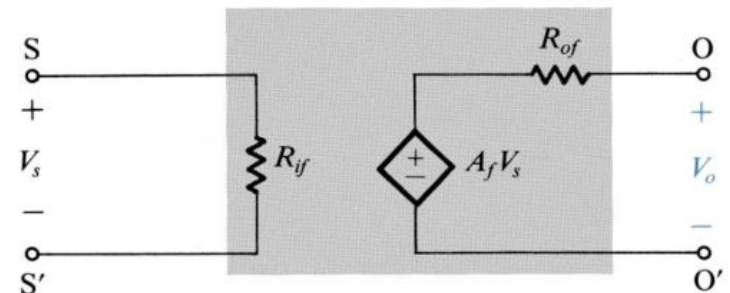
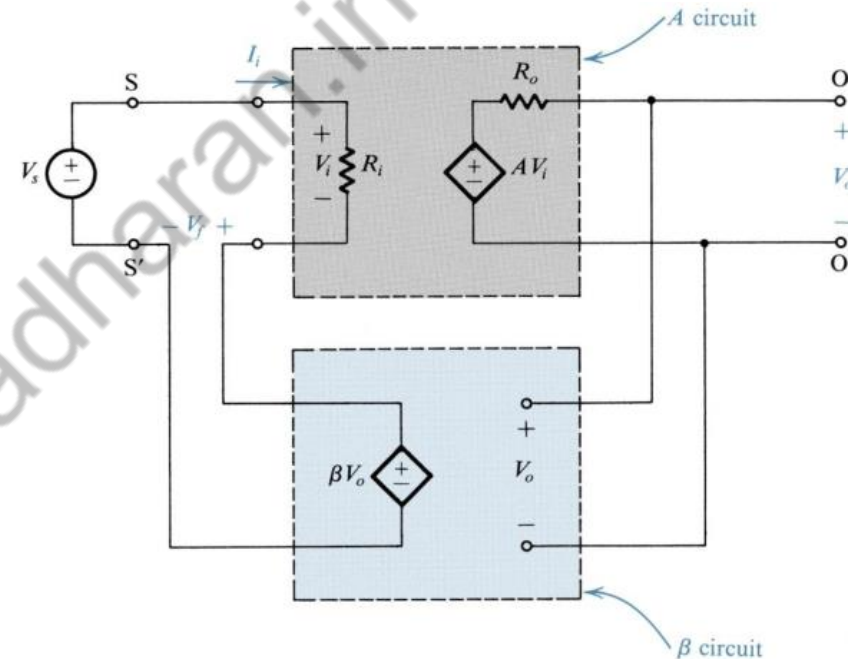
$$R_{if} = \frac{V_s}{I_i} = \frac{V_s}{V_i/R_i} = R_i \frac{V_s}{V_i} = R_i \frac{V_i + \beta A V_i}{V_i} = R_i (1 + A\beta)$$

$$V_o = I_o R_o - \beta A V_o$$

$$\frac{V_o}{I_o} = R_{of} = \frac{R_o}{1 + \beta A}$$

β, A, A_f have no unit

Loop gain has no unit



Series-Series Feedback Amplifier (Current-Voltage Feedback)

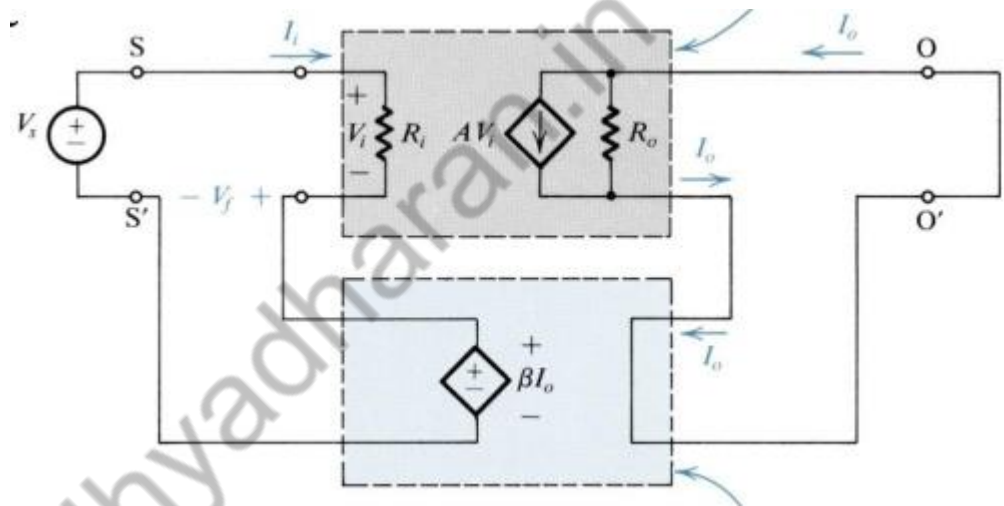
$$I_0 = G_M V_i = G_M (V_S + \beta I_0)$$

$$\frac{I_0}{V_S} = G_{Mf} = \frac{G_M}{1 + \beta G_M}$$

$$V_S = I_i R_i + \beta I_0$$

$$V_S = I_i R_i + \frac{\beta G_M V_S}{1 + \beta G_M}$$

$$\frac{V_S}{I_i} = R_{if} = (1 + \beta G_M) R_i$$



$$I_{tst} = \frac{V_{tst}}{R_0} - \beta G_M I_{tst}$$

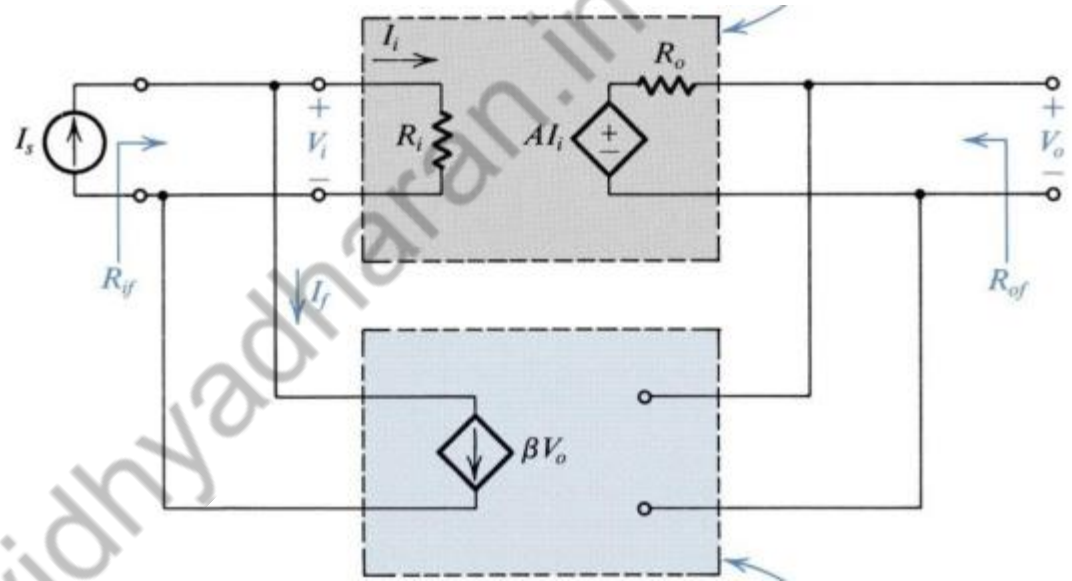
$$R_{of} = \frac{V_{tst}}{I_{tst}} = R_0 (1 + \beta G_M)$$

G_M, G_{Mf} transconductance: A/V

β Resistance: Ohms

Loop gain has no unit

Shunt-Shunt Feedback Amplifier (Voltage-Current Feedback)



$$V_o = R_M I_i = R_M (I_s + \beta V_o)$$

$$\frac{V_o}{I_s} = R_{Mf} = \frac{R_M}{1 + \beta R_M}$$

$$I_s = I_f + \frac{V_i}{R_i}$$

$$I_s = \beta R_M I_i + \frac{V_i}{R_i}$$

$$I_s = \beta R_M \frac{V_i}{R_i} + \frac{V_i}{R_i}$$

$$\frac{V_i}{I_s} = R_{if} = \frac{R_i}{1 + \beta R_M}$$

$$V_o = I_o R_o - \beta R_M V_o$$

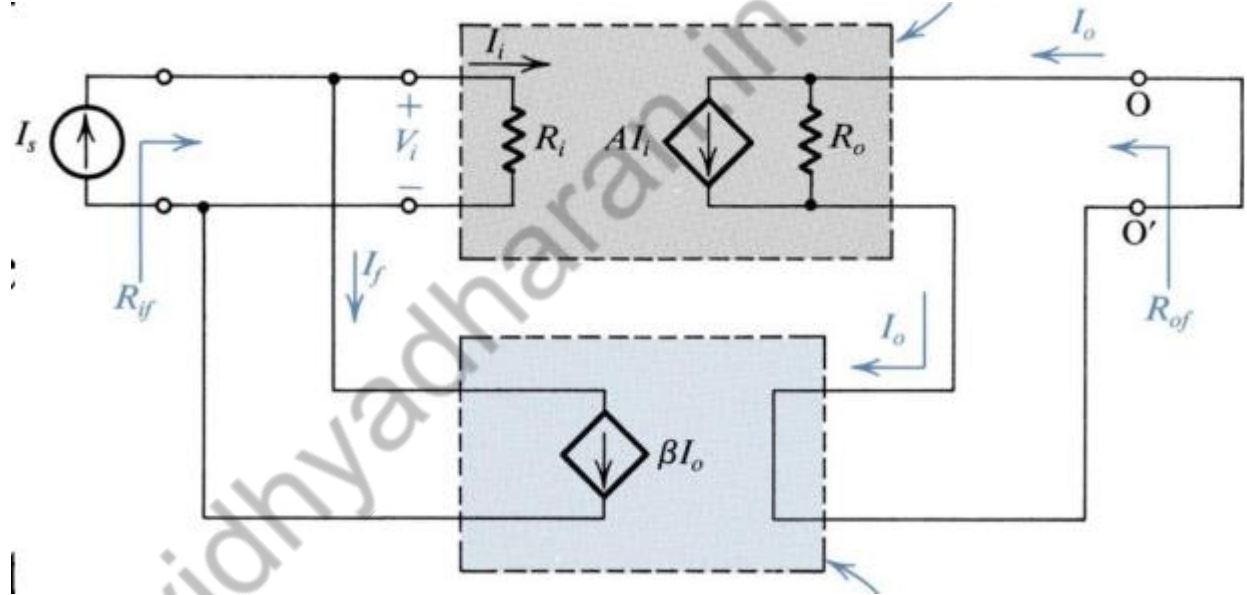
$$\frac{V_o}{I_o} = R_{of} = \frac{R_o}{1 + R_M A}$$

R_M, R_{Mf} transresistance: Ohms

β transconductance: A/V

Loop gain has no unit

Shunt-Series Feedback Amplifier (Current-Current Feedback)



$$\frac{I_o}{I_s} = A_{If} = \frac{A_I}{1 + \beta A_I}$$

$$\frac{V_i}{I_s} = R_{if} = \frac{R_i}{1 + \beta A_I}$$

$$R_{of} = \frac{V_{tst}}{I_{tst}} = \frac{R_o}{1 + \beta A_I}$$

β, A_I, A_{If} have no unit

Loop gain has no unit

Analysis of Feedback Amplifiers

To find the input circuit:

1. Set $V_o = 0$ for voltage sampling. In other words, short the output node.
2. Set $I_o = 0$ for current sampling. In other words, open the output loop.

To find the output circuit:

1. Set $V_i = 0$ for shunt comparison. In other words, short the input node.
2. Set $I_i = 0$ for series comparison. In other words, open the input loop.

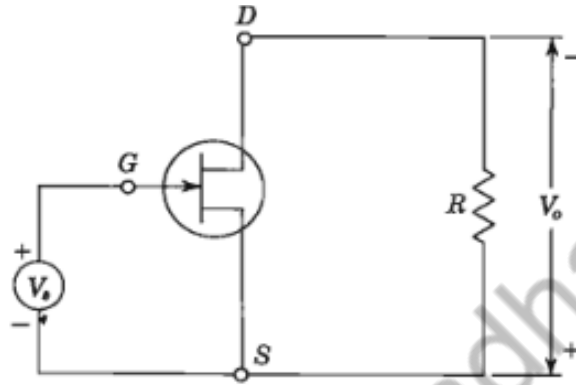
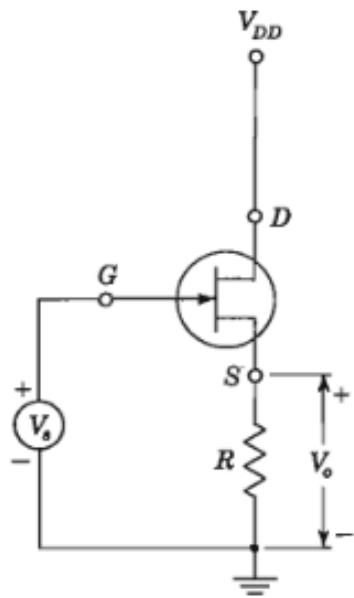
These procedures ensure that the feedback is reduced to zero without altering the loading on the basic amplifier.

Analysis of Feedback Amplifiers

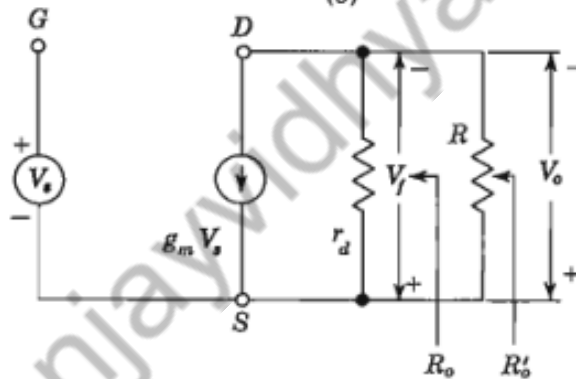
The complete analysis of a feedback amplifier is obtained by carrying out the following steps:

1. Identify the topology. (a) Is the feedback signal X_f a voltage or a current? In other words, is X_f applied in series or in shunt with the external excitation? (b) Is the sampled signal X_o a voltage or a current? In other words, is the sampled signal taken at the output node or from the output loop?
2. Draw the basic amplifier circuit without feedback, following the rules listed above.
3. Use a Thévenin's source if X_f is a voltage and a Norton's source if X_f is a current.
4. Replace each active device by the proper model (for example, the hybrid- Π model for a transistor at high frequencies or the h -parameter model at low frequencies).
5. Indicate X_f and X_o on the circuit obtained by carrying out steps 2, 3, and 4. Evaluate $\beta = X_f/X_o$.
6. Evaluate A by applying KVL and KCL to the equivalent circuit obtained after step 4.
7. From A and β , find D , A_f , R_{if} , R_{of} , and R'_{of} .

Example - 1 Source Follower



(b)



$$A_v = \frac{V_o}{V_i} = \frac{g_m V_s r_d R}{(r_d + R) V_s} = \frac{\mu R}{r_d + R}$$

where $\mu = g_m r_d$

$$D = 1 + \beta A_v = 1 + \frac{\mu R}{r_d + R} = \frac{r_d + (1 + \mu)R}{r_d + R}$$

$$A_{v_f} = \frac{A_v}{D} = \frac{\mu R}{r_d + (1 + \mu)R}$$

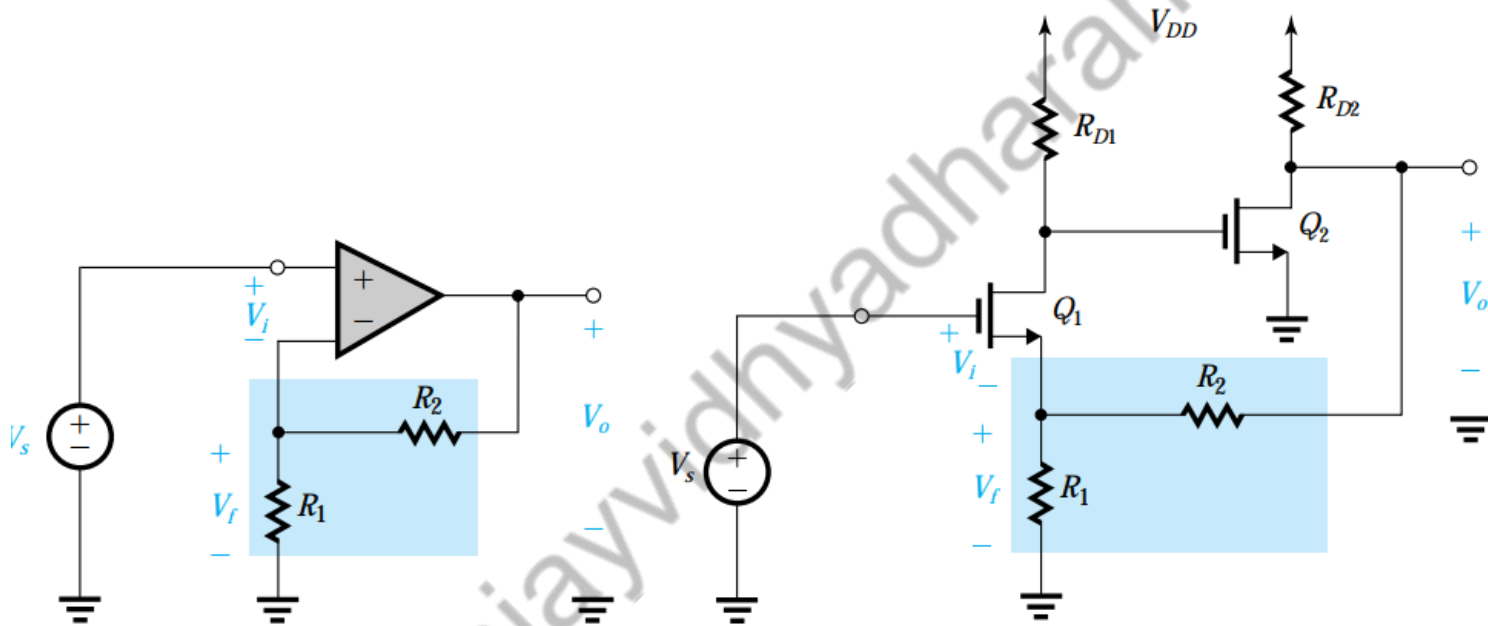
Since $R_i = \infty$, then

$$R_{if} = R_i D = \infty$$

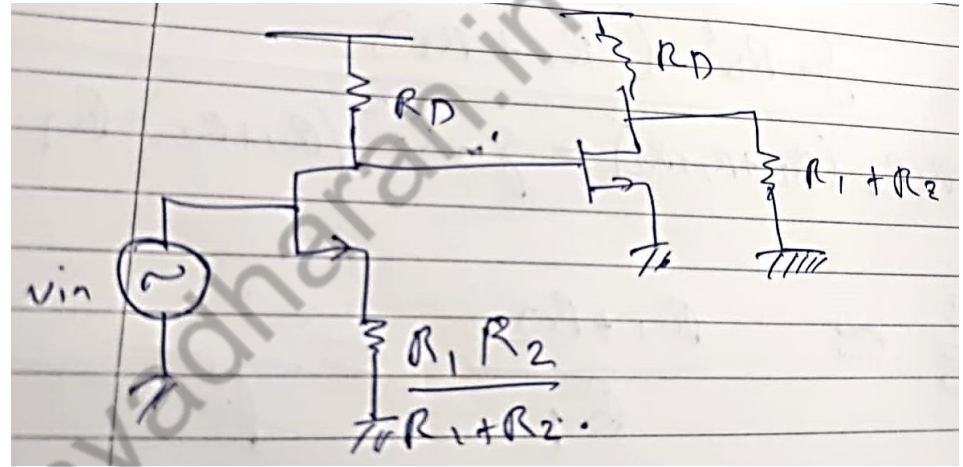
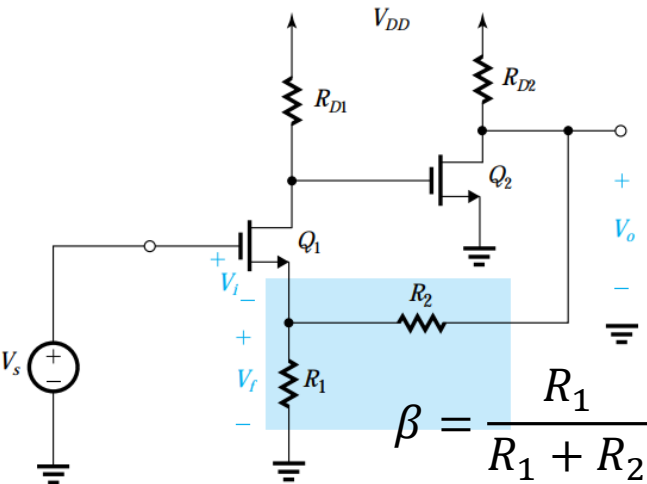
$$R'_{of} = \frac{R'_o}{D} = \frac{R r_d}{R + r_d} \frac{r_d + R}{r_d + (\mu + 1)R} = \frac{R r_d}{r_d + (\mu + 1)R}$$

We must now draw the basic amplifier without feedback. To find the input circuit, set $V_o = 0$, and hence V_s appears directly between G and S . To find the output circuit, set $I_i = 0$ (the input loop is opened), and hence R appears only in the output loop. Following these rules we obtain Fig. 13-12b.

Example - 2



Example - 2



$$G_1 = \frac{R_D(R_1 + R_2)}{R_1 R_2}$$

$$G_2 = \frac{g_{m2} R_D (R_1 + R_2)}{R_D + R_1 + R_2}$$

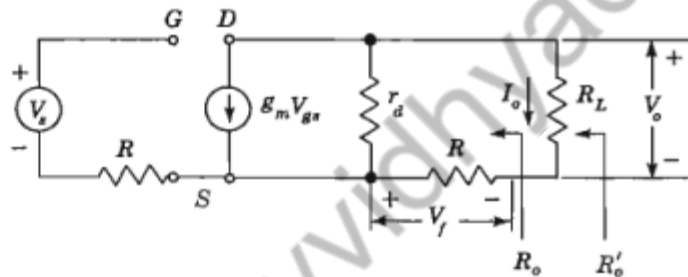
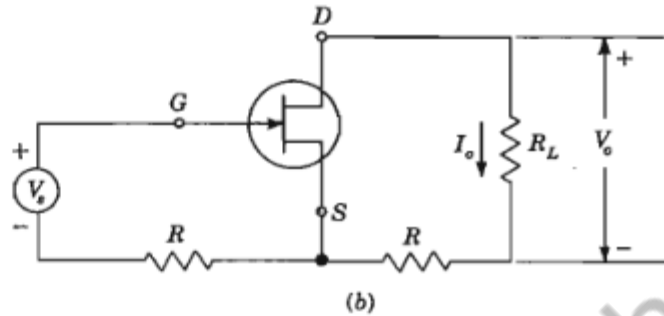
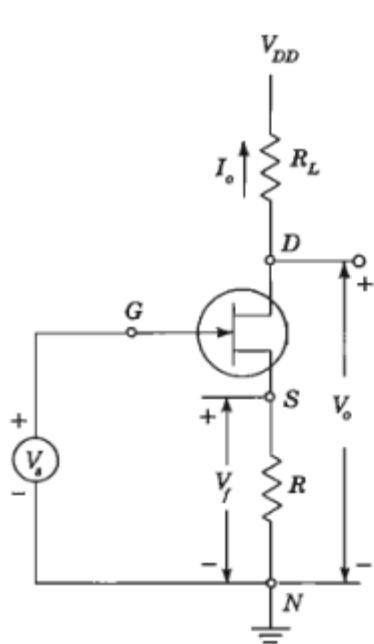
$$A_0 = \frac{g_{m2} R_D^2 (R_1 + R_2)^2}{R_1 R_2 (R_D + R_1 + R_2)}$$

$$\beta A_0 = \frac{g_{m2} R_D^2 (R_1 + R_2) R_1}{R_1 R_2 (R_D + R_1 + R_2)}$$

$$1 + \beta A_0 = \frac{R_1 R_2 (R_D + R_1 + R_2) + g_{m2} R_D^2 (R_1 + R_2) R_1}{R_1 R_2 (R_D + R_1 + R_2)}$$

$$A_f = \frac{A_0}{1 + \beta A_0} = \frac{g_{m2} R_D^2 (R_1 + R_2)^2}{R_1 R_2 (R_D + R_1 + R_2) + g_{m2} R_D^2 (R_1 + R_2) R_1} \approx \frac{R_1 + R_2}{R_1} = \frac{1}{\beta}$$

Example - 3



Since $R_i = \infty$, then

$$R_{if} = R_i D = \infty$$

$$R_o = r_d + R$$

$$R_{of} = R_o(1 + \beta G_m)$$

$$= (r_d + R) \frac{r_d + (\mu + 1)R}{r_d + R} =$$

$$= r_d + (\mu + 1)R$$

$$G_M = \frac{I_o}{V_i} = \frac{I_o}{V_s} = \frac{-g_m r_d}{r_d + R_L + R}$$

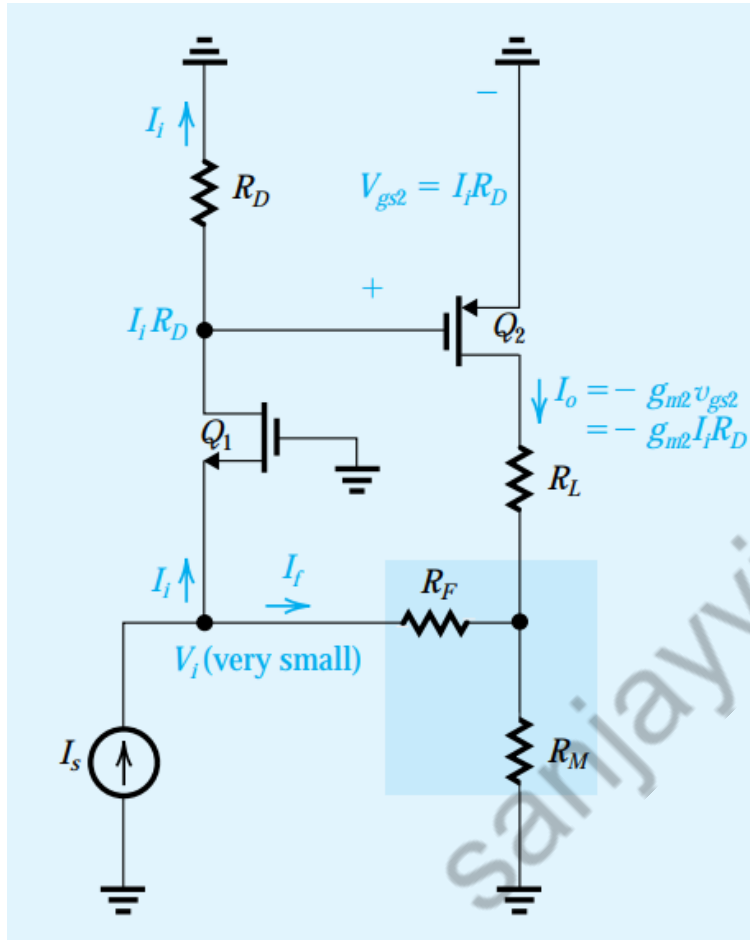
$$= \frac{-\mu}{r_d + R_L + R}$$

$$D = 1 + \beta G_M = 1 + \frac{\mu R}{r_d + R_L + R} = \frac{r_d + R_L + (\mu + 1)R}{r_d + R_L + R}$$

$$G_{Mf} = \frac{G_M}{D} = \frac{-\mu}{r_d + R_L + (\mu + 1)R}$$

$$\beta = \frac{V_f}{I_o} = -R$$

Example - 4



$$I_o = -g_{m2} R_D I_i$$

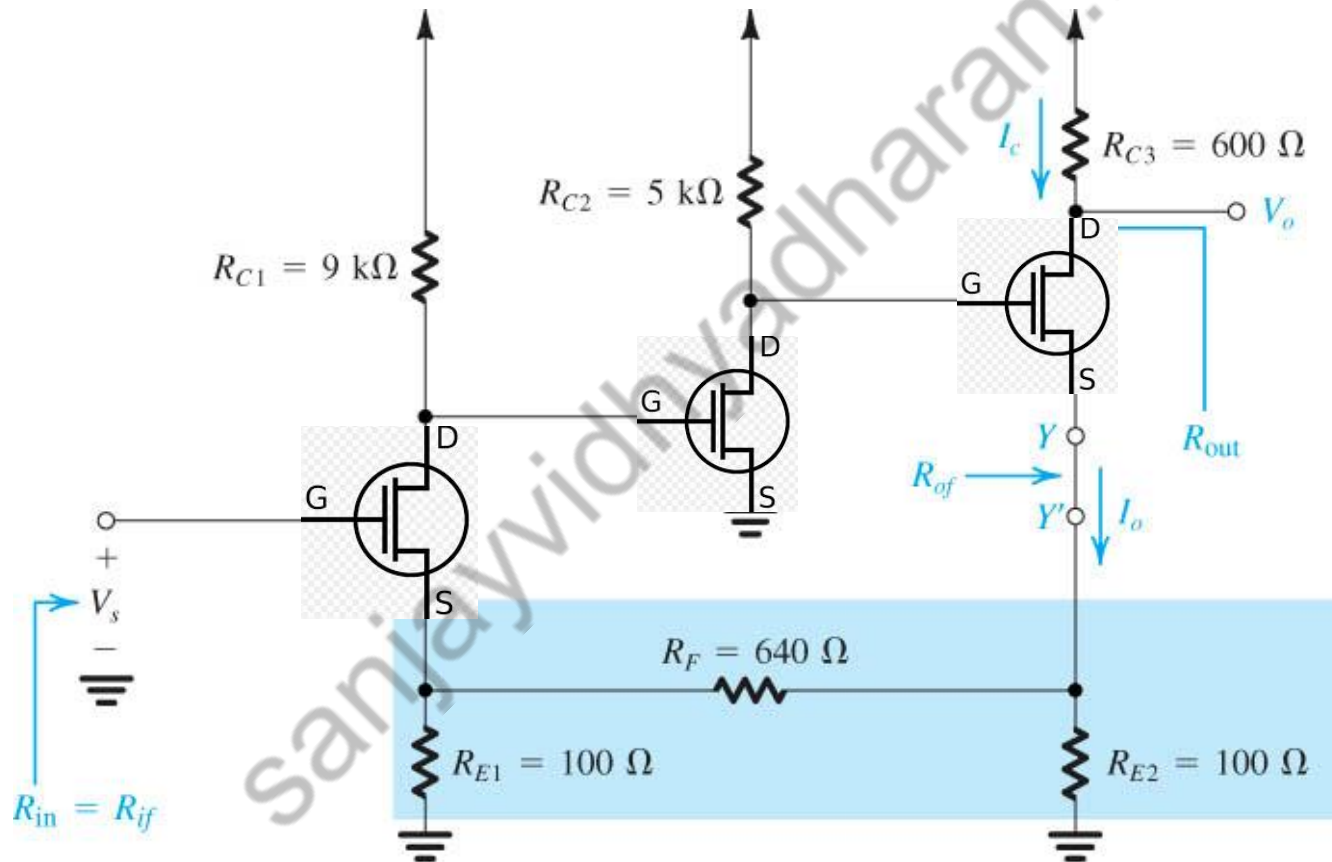
$$A \equiv \frac{I_o}{I_i} = -g_{m2} R_D$$

$$\beta \equiv \frac{I_f}{I_o} \approx -\frac{R_M}{R_F + R_M}$$

$$A_f \equiv \frac{I_o}{I_s} = -\frac{g_{m2} R_D}{1 + g_{m2} R_D / \left(1 + \frac{R_F}{R_M}\right)}$$

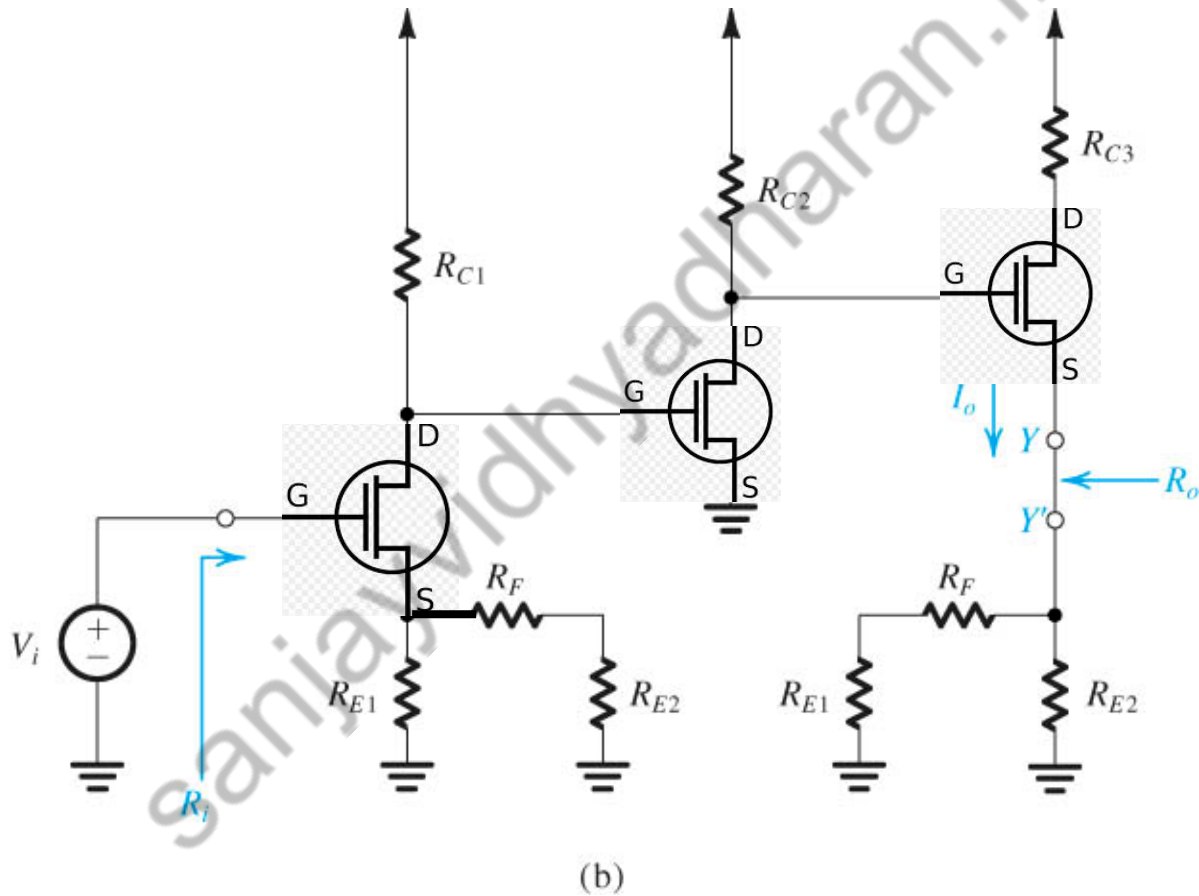
$$I_i = \frac{(R_F + R_M) I_s}{R_F + R_M + \frac{1}{g_{m1}}}$$

Example - 5

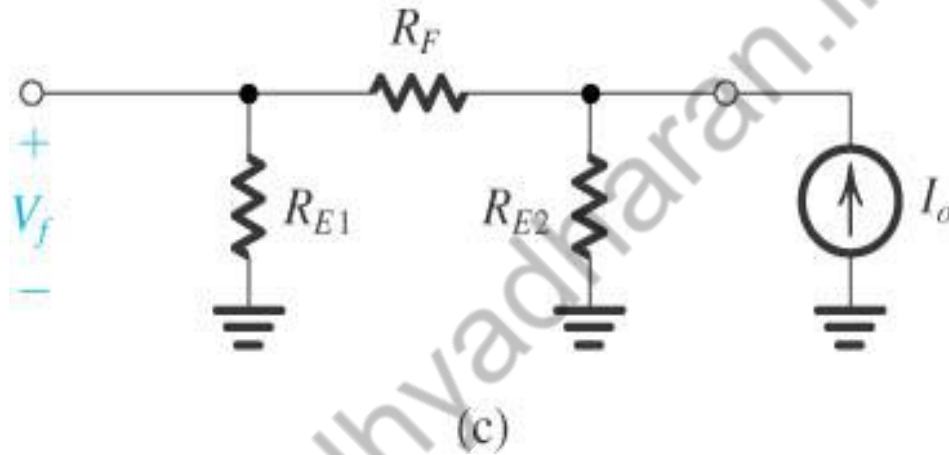


(a)

Example - 5



Example - 5



$$\beta \equiv \frac{V_f}{I_o} = \frac{R_{E2}}{R_{E2} + R_F + R_{E1}} \times R_{E1}$$

Thankyou

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