



Analog IC Design : 2022-23

Lecture 7

DC Voltage and DC Current Sources

By Dr. Sanjay Vidhyadharan

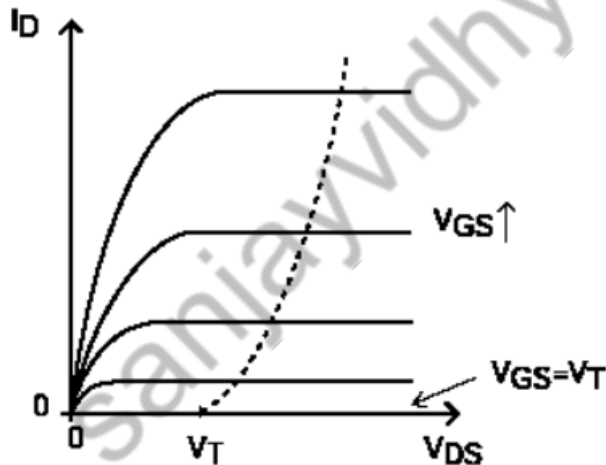
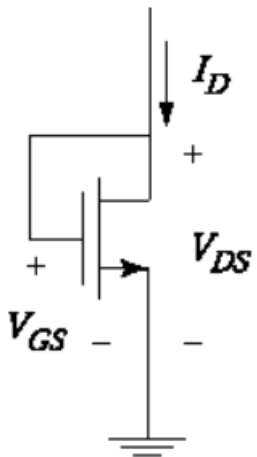
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DC Voltage Sources

Characteristics of DC Voltage Sources :

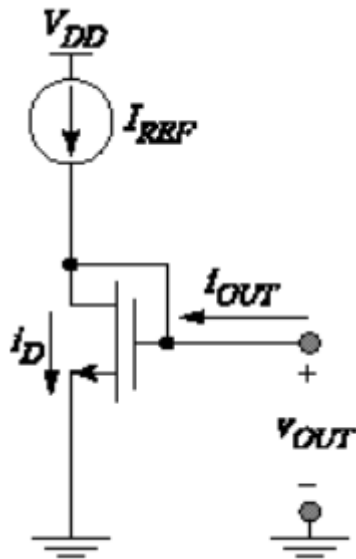
- A well controlled output voltage

MOSFET connected in “diode configuration”



$$I_D = \frac{W}{2L} \mu_n C_{ox} (V_{GS} - V_{Tn})^2 = \frac{W}{2L} \mu_n C_{ox} (V_{DS} - V_{Tn})^2$$

DC Voltage Sources



$V_{GS} = V_{DS}$ takes a value needed to sink current

$$i_D = I_{REF} + i_{OUT} = \frac{W}{2L} \mu_n C_{ox} (v_{OUT} - V_{Tn})^2$$

Then:

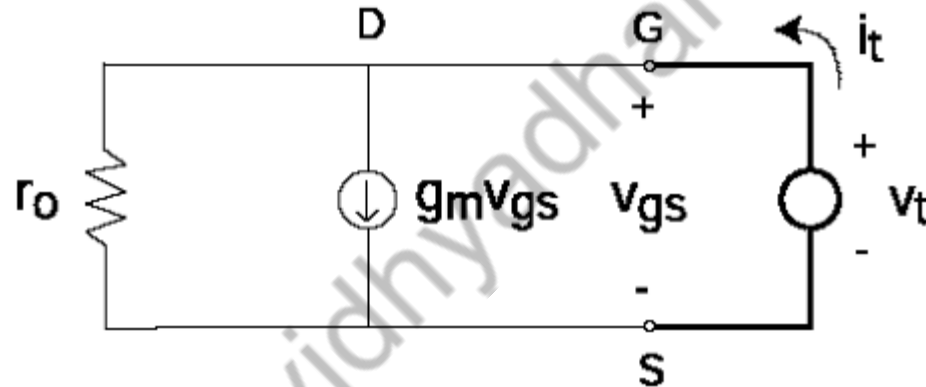
$$i_{OUT} = \frac{W}{2L} \mu_n C_{ox} (v_{OUT} - V_{Tn})^2 - I_{REF}$$

Solving for v_{OUT} :

$$v_{OUT} = V_{Tn} + \sqrt{\frac{I_{REF} + i_{OUT}}{\frac{W}{2L} \mu_n C_{ox}}}$$

DC Voltage Sources

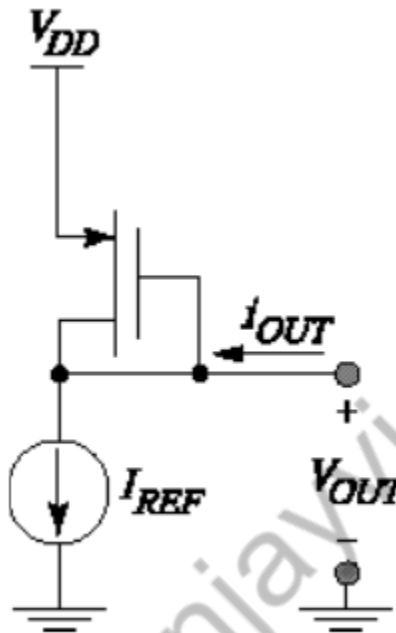
Small Signal Equivalent Circuit Model:



$$R_{out} = \frac{1}{g_m} \parallel r_o \approx \frac{1}{g_m}$$

DC Voltage Sources

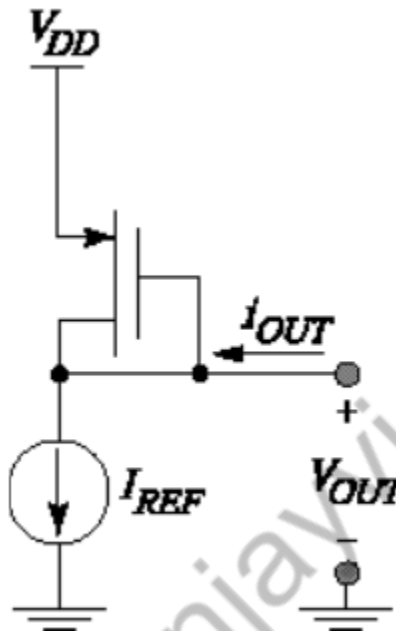
PMOS voltage source



Same operation and characteristics as NMOS voltage source. PMOS needs to be larger to attain the same R_{out} .

DC Voltage Sources

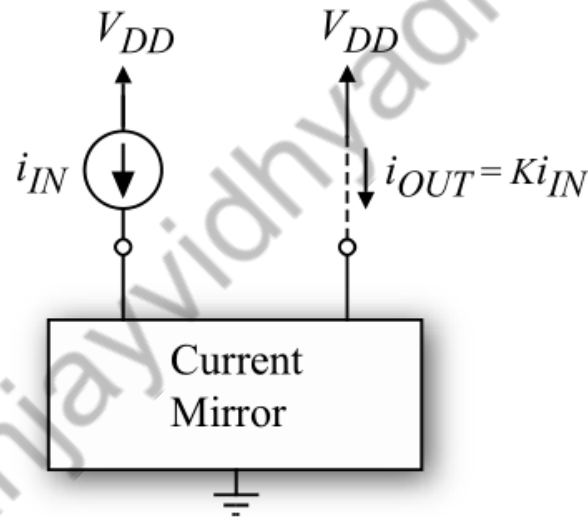
PMOS voltage source



Same operation and characteristics as NMOS voltage source. PMOS needs to be larger to attain the same R_{out} .

DC CURRENT MIRRORS

A current mirror replicates the input current of a current sink or current source as an output current. The output current may be identical to the input current or can be a scaled version of it.

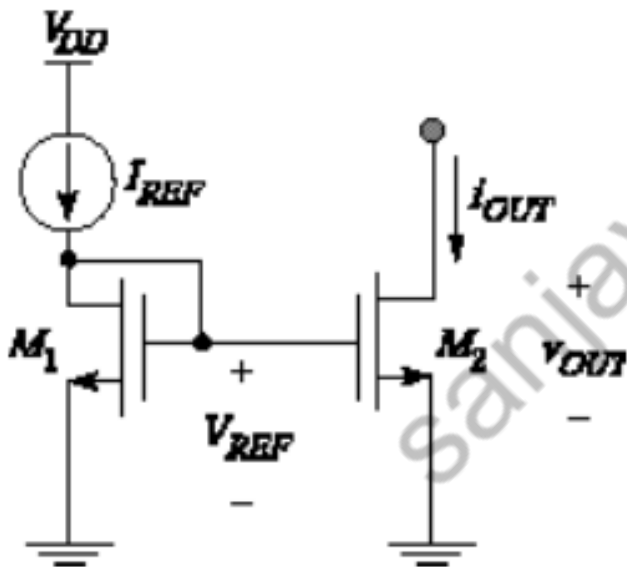


DC Current Sources

Characteristics of Current Sources

- A well controlled output current
- Supplied current does not depend on output voltage
⇒ High Norton Resistance

Current Mirror Circuit

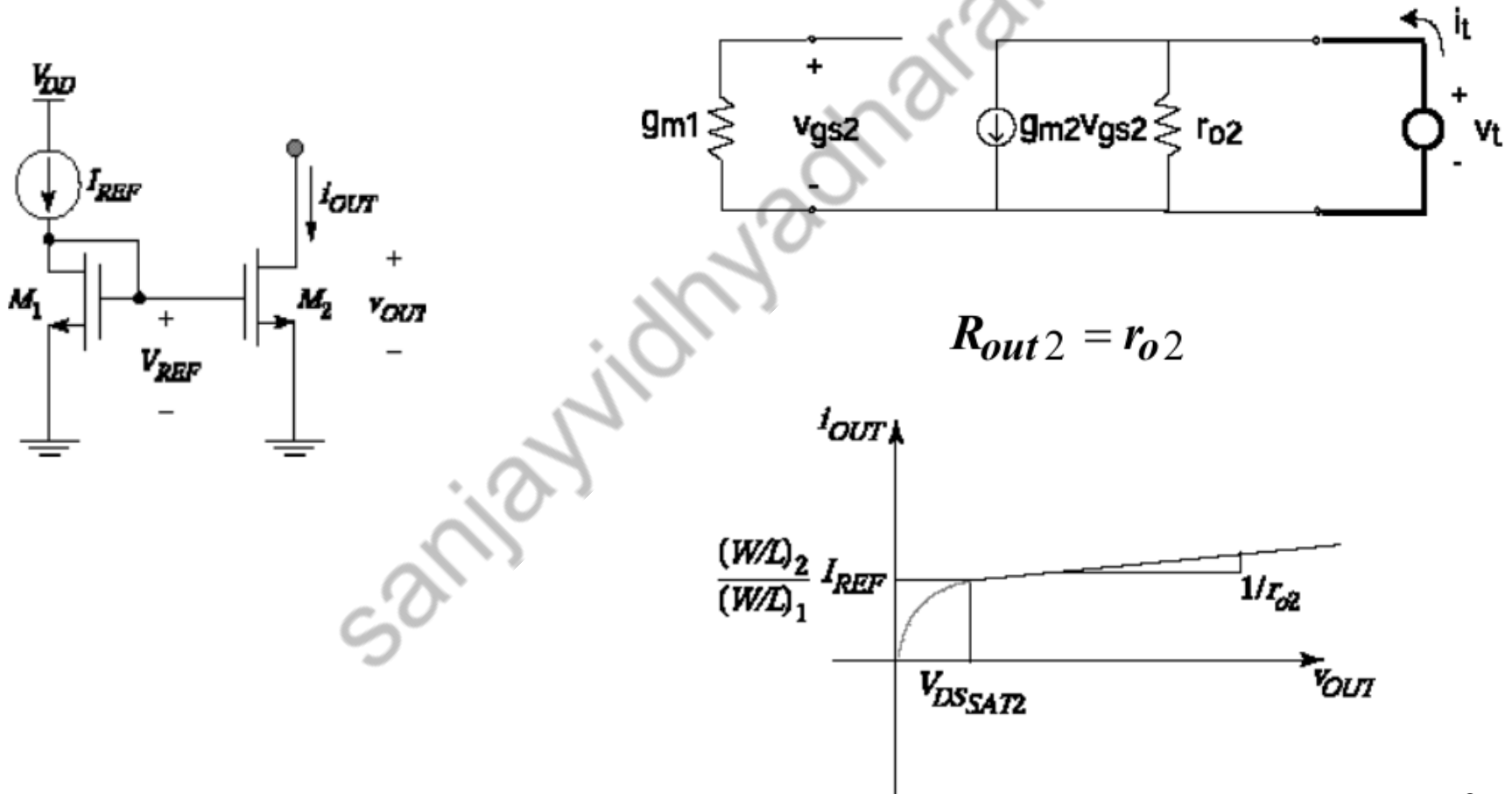


$$I_{OUT} \approx \frac{1}{2} \left(\frac{W}{L} \right)_2 \mu_n C_{ox} (V_{REF} - V_{Tn})^2$$
$$I_{REF} \approx \frac{1}{2} \left(\frac{W}{L} \right)_1 \mu_n C_{ox} (V_{REF} - V_{Tn})^2$$

$$I_{OUT} = I_{REF} \frac{\left(\frac{W}{L} \right)_2}{\left(\frac{W}{L} \right)_1}$$

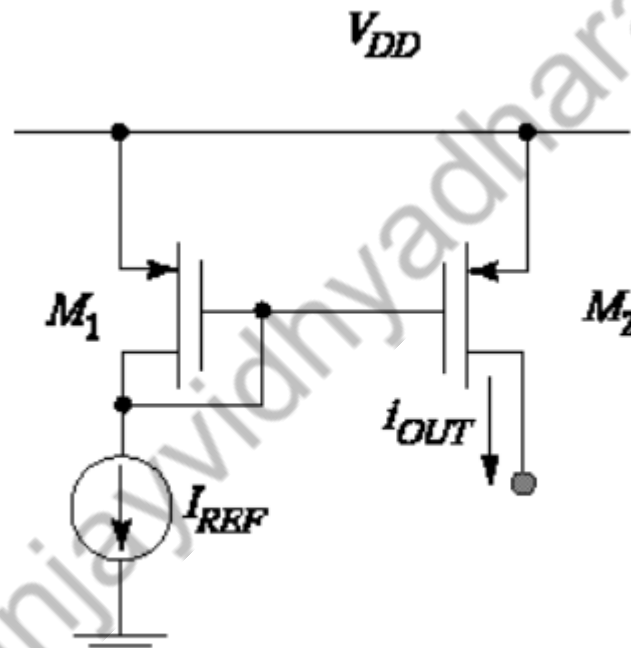
DC Current Sources

Small Signal Equivalent Circuit Model:



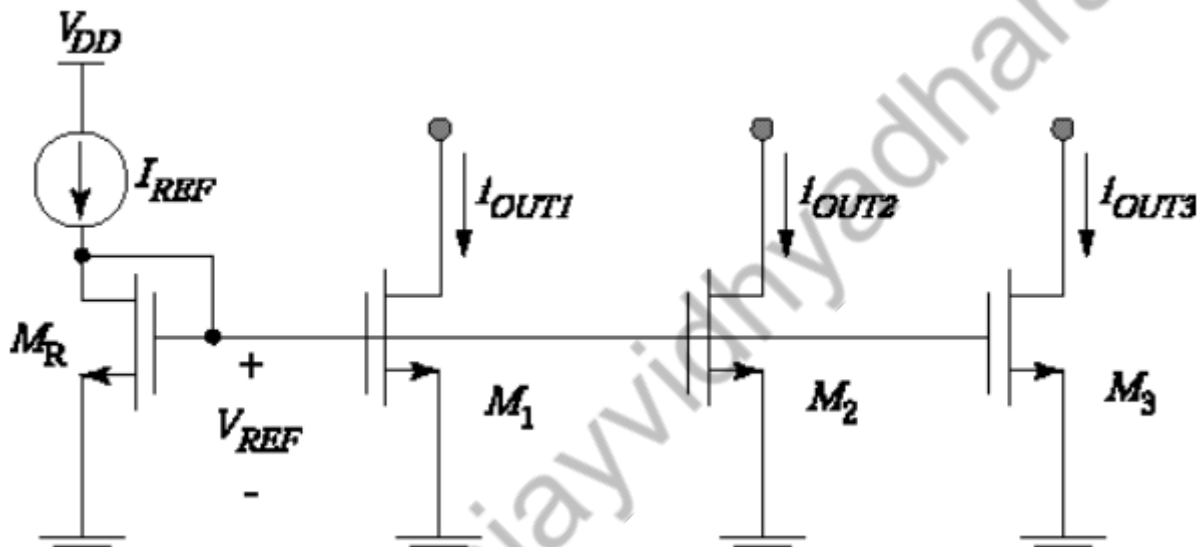
DC Current Sources

PMOS Current Source



Current Mirrors

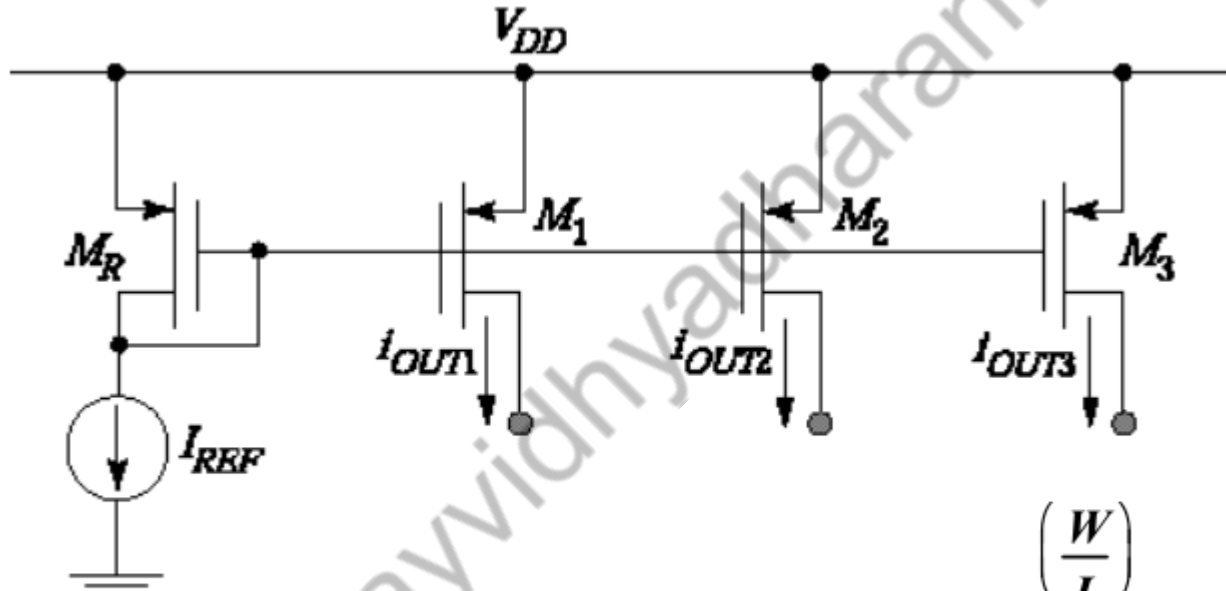
NMOS Current Mirror



$$I_{OUTn} = I_{REF} \frac{\left(\frac{W}{L}\right)_n}{\left(\frac{W}{L}\right)_R}$$

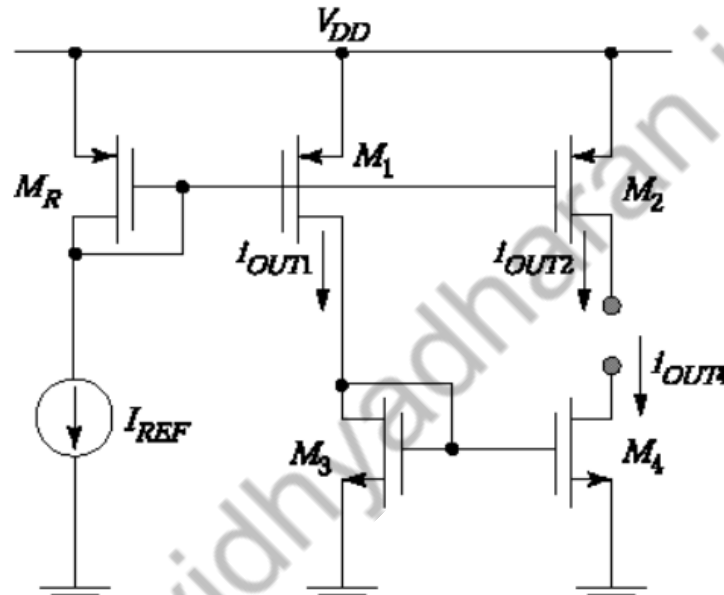
Current Mirrors

PMOS Current Mirror



$$I_{OUTn} = I_{REF} \frac{\left(\frac{W}{L}\right)_n}{\left(\frac{W}{L}\right)_R}$$

Current Mirrors

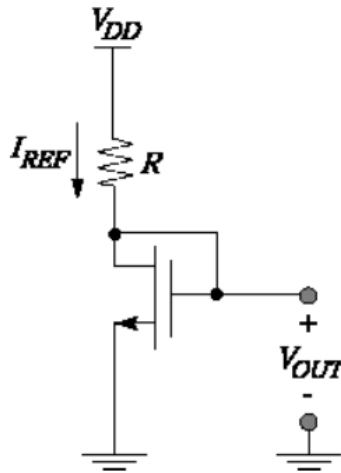


$$I_{OUT1} = I_{REF} \frac{\left(\frac{W}{L}\right)_1}{\left(\frac{W}{L}\right)_R}$$

$$I_{OUT2} = I_{REF} \frac{\left(\frac{W}{L}\right)_2}{\left(\frac{W}{L}\right)_R}$$

$$I_{OUT4} = I_{OUT1} \frac{\left(\frac{W}{L}\right)_4}{\left(\frac{W}{L}\right)_3} = I_{REF} \frac{\left(\frac{W}{L}\right)_4}{\left(\frac{W}{L}\right)_3} \frac{\left(\frac{W}{L}\right)_1}{\left(\frac{W}{L}\right)_R}$$

Generating I_{REF}



$$I_{REF} = \frac{V_{DD} - V_{OUT}}{R}$$

$$V_{OUT} = V_{Tn} + \sqrt{\frac{I_{REF}}{\frac{W}{2L} \mu_n C_{ox}}}$$

For large W/L:
$$I_{REF} \approx \frac{V_{DD} - V_{Tn}}{R}$$

Advantages

– I_{REF} set by value of resistor

Disadvantages

– V_{DD} also affects I_{REF} .

– V_{Tn} and R are functions of temperature

In the real world, more sophisticated circuits are used to generate I_{REF} that are V_{DD} and T independent.

Influence of the Channel Modulation Parameter λ

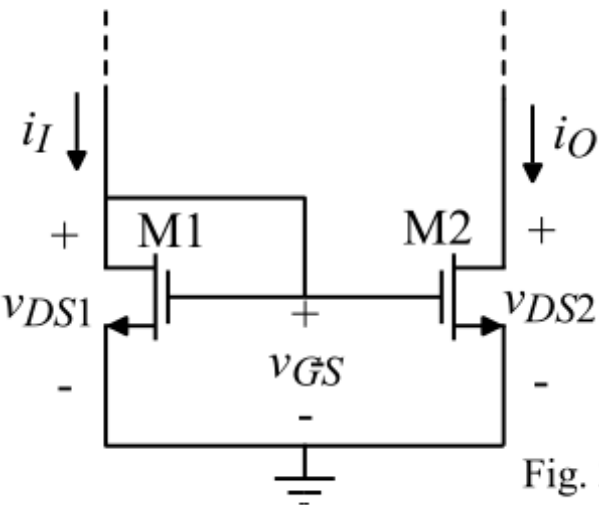


Fig. 1

Assume that $v_{DS2} > v_{GS} - V_{T2}$, then

$$\frac{i_O}{i_I} = \left(\frac{L_1 W_2}{W_1 L_2} \right) \left(\frac{V_{GS} - V_{T2}}{V_{GS} - V_{T1}} \right)^2 \left[\frac{1 + \lambda v_{DS2}}{1 + \lambda v_{DS1}} \left(\frac{K_2'}{K_1'} \right) \right]$$

If the transistors are matched, then $K_1' = K_2'$ and $V_{T1} = V_{T2}$

$$\frac{i_O}{i_I} = \left(\frac{L_1 W_2}{W_1 L_2} \right) \left(\frac{1 + \lambda v_{DS2}}{1 + \lambda v_{DS1}} \right)$$

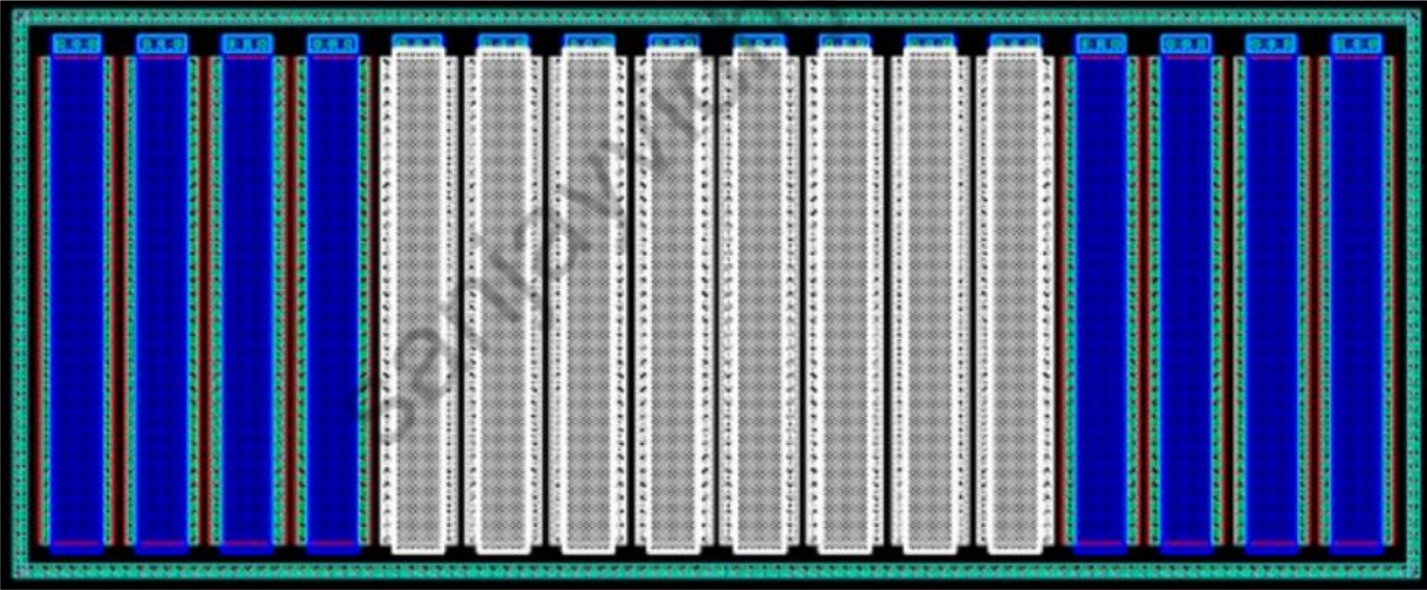
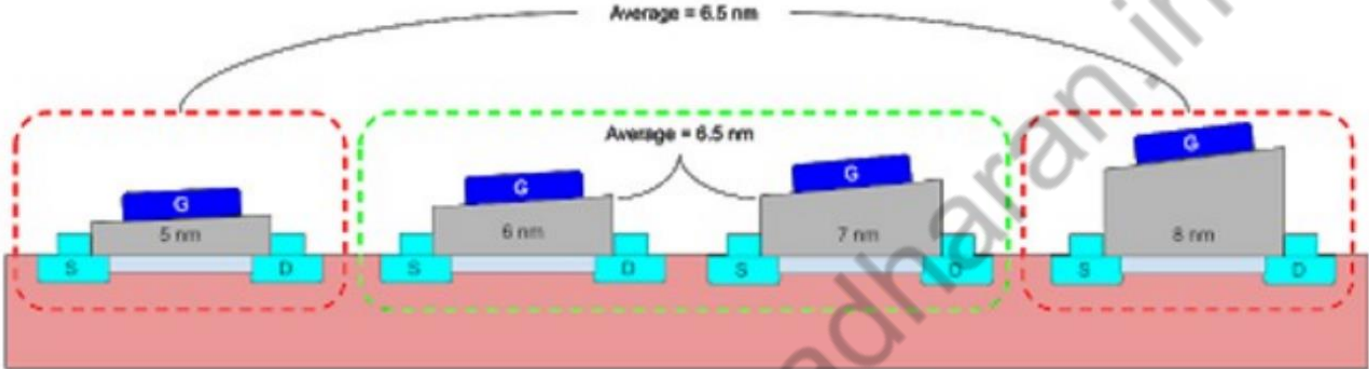
If $v_{DS1} = v_{DS2}$, then

$$\frac{i_O}{i_I} = \left(\frac{L_1 W_2}{W_1 L_2} \right)$$

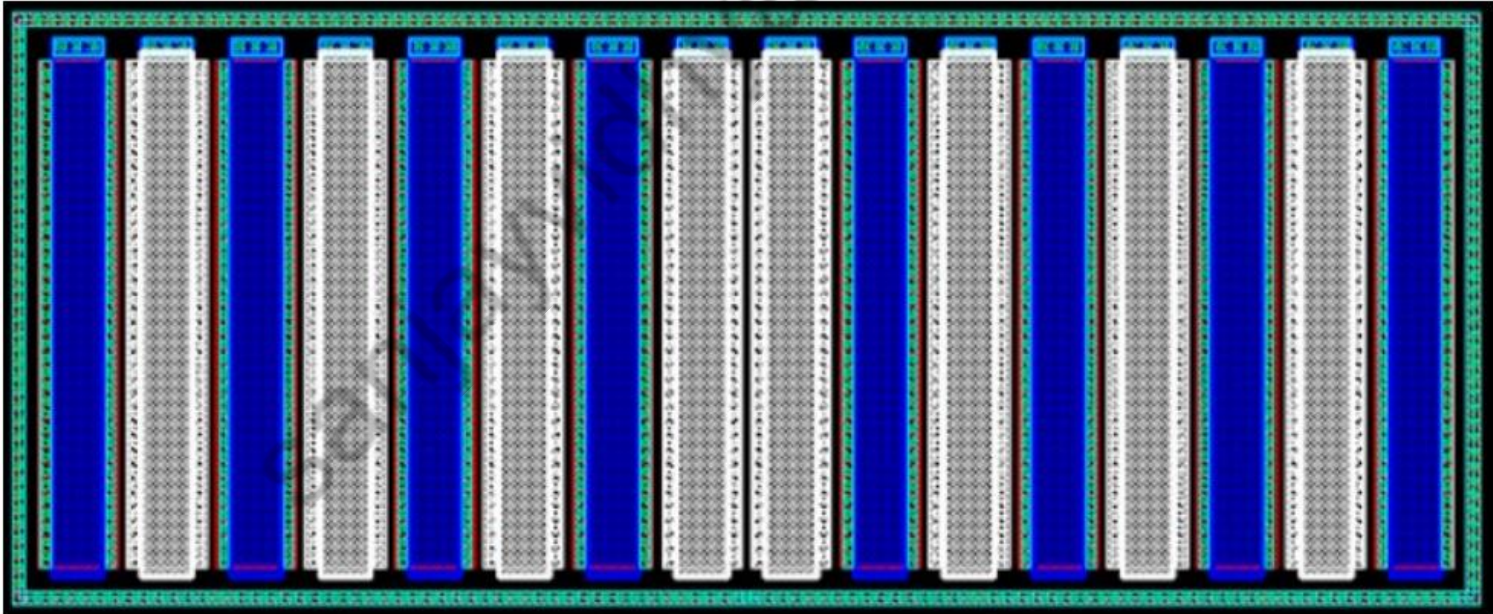
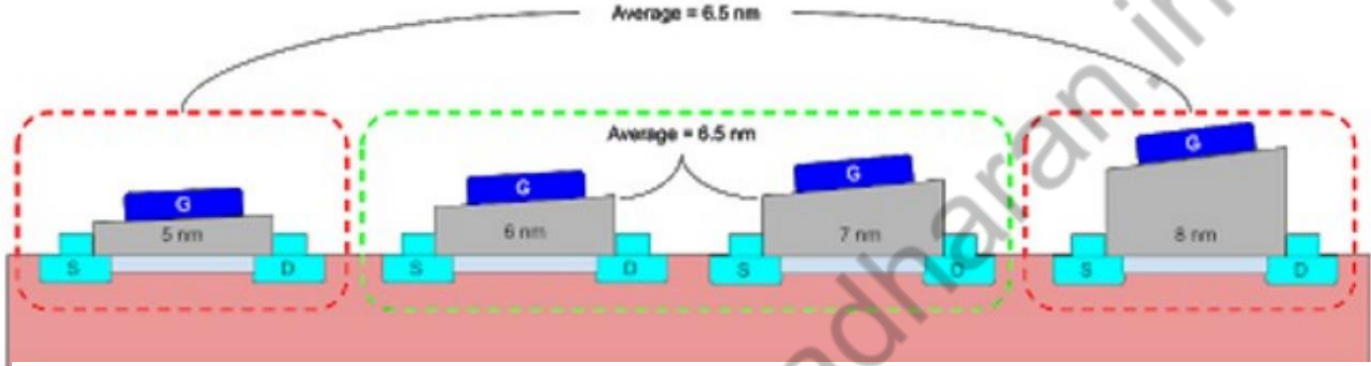
Therefore the sources of error are:

- 1.) $v_{DS1} \neq v_{DS2}$
- 2.) M1 and M2 are not matched.

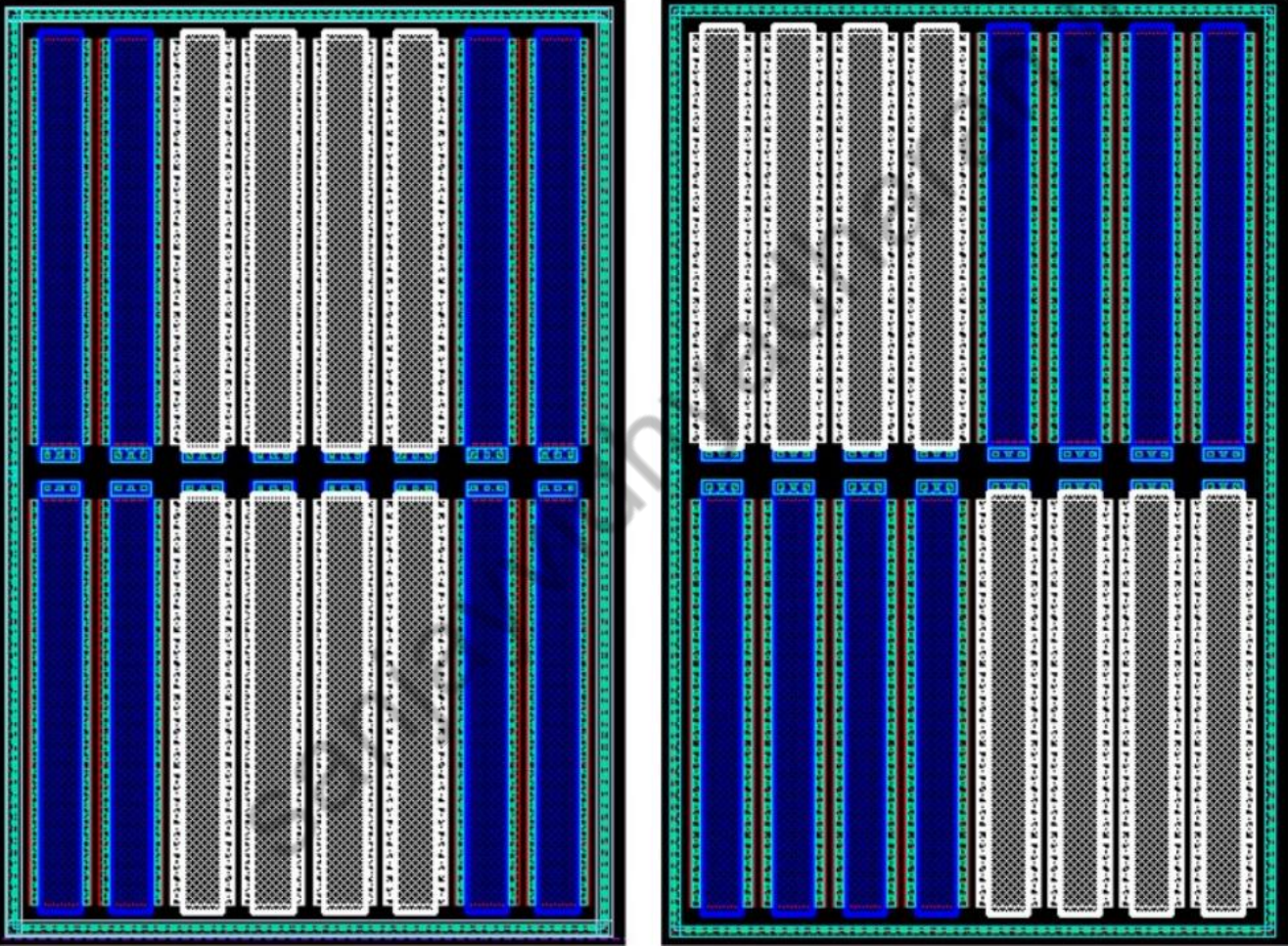
Common centroid design evens out the effect of the process variation.



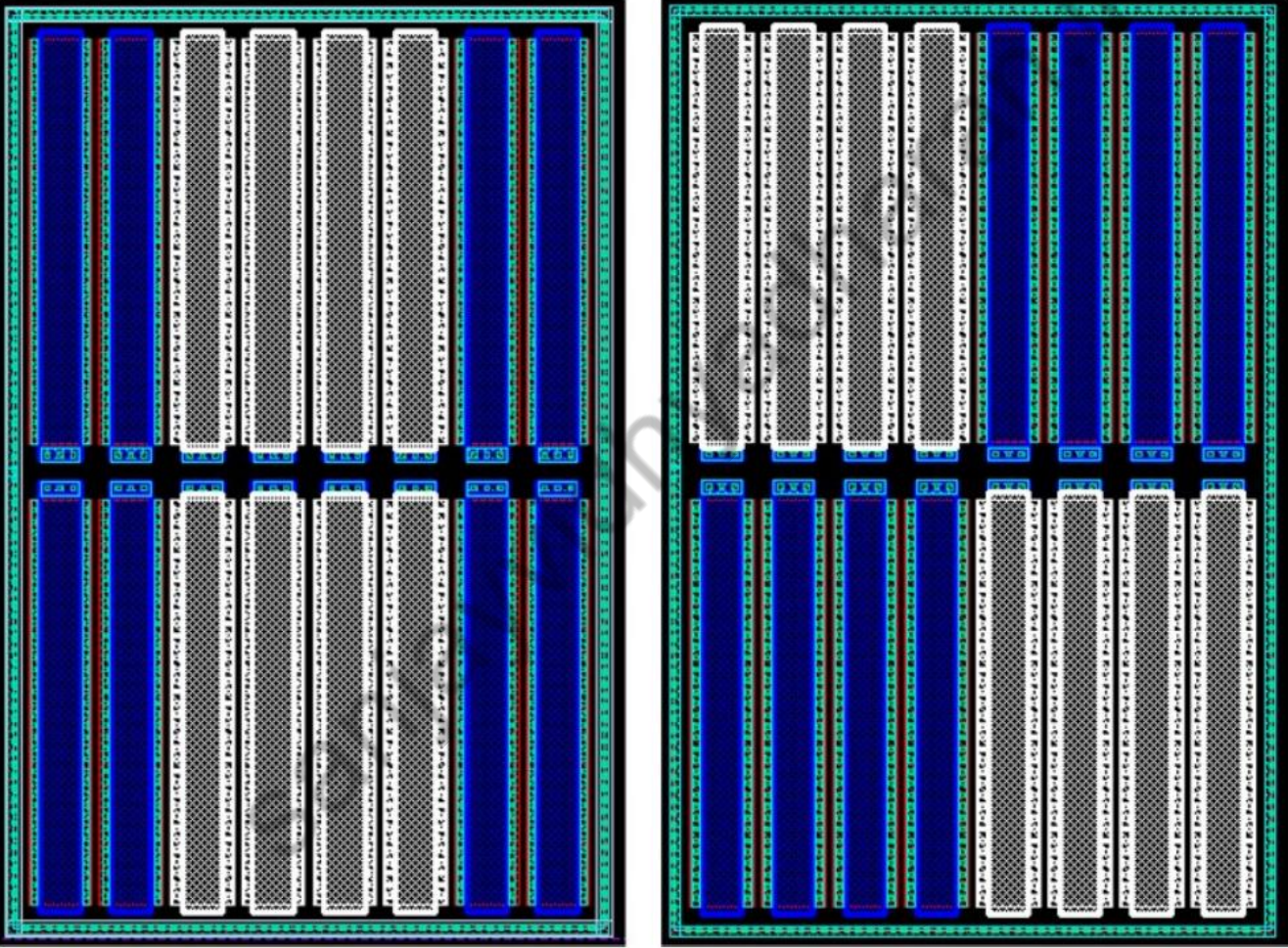
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Common centroid design evens out the effect of the process variation.



Common centroid design evens out the effect of the process variation.



Current Mirror Specifications

- Small-signal output resistance R_O .
- Minimum output voltage V_{Omin} .
- Current gain error definition:

$$E = \frac{I_{OUT} - I_{OUT_ideal}}{I_{OUT_ideal}}$$

- Two types of error:
 - systematic error: error caused by circuit structure.
 - Random error: error caused by process variations.
- These two types of error are commonly seen in many analog circuits.
- A robust design is to minimize both systematic error and random error.

Current Mirror Analysis

- As $V_{GS1} = V_{GS2}$ and assuming matched $V_{TH1} = V_{TH2}$

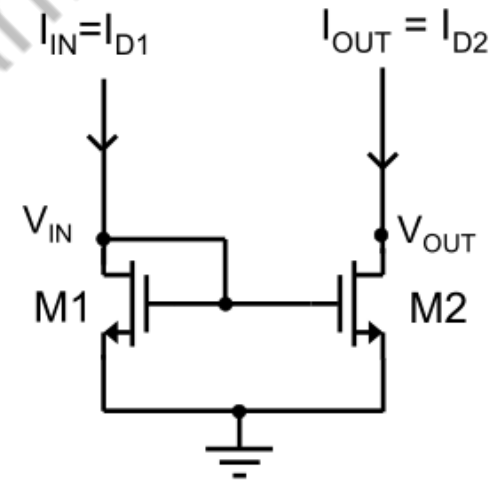
$$\frac{I_{OUT}}{I_{IN}} = \frac{\left(\frac{W}{L}\right)_2 (1 + \lambda V_{OUT})}{\left(\frac{W}{L}\right)_1 (1 + \lambda V_{IN})}$$

- The output resistance of current source is the output resistance of M2

$$R_o = \frac{1}{\lambda I_{D2}} = \frac{1}{\lambda I_{OUT}}$$

- Normally, larger L is used so that λ effect is reduced and the output resistance is higher.
- The current gain systematic error is:

$$E = \frac{I_{OUT} - I_{OUT_ideal}}{I_{OUT_ideal}} = \frac{(1 + \lambda V_{OUT})}{(1 + \lambda V_{IN})} - 1 = \frac{\lambda}{(1 + \lambda V_{IN})} (V_{OUT} - V_{IN}) \approx \lambda (V_{OUT} - V_{IN})$$



$$I_{OUT_ideal} = \frac{\left(\frac{W}{L}\right)_2}{\left(\frac{W}{L}\right)_1} I_{IN}$$

Current Mirror Analysis

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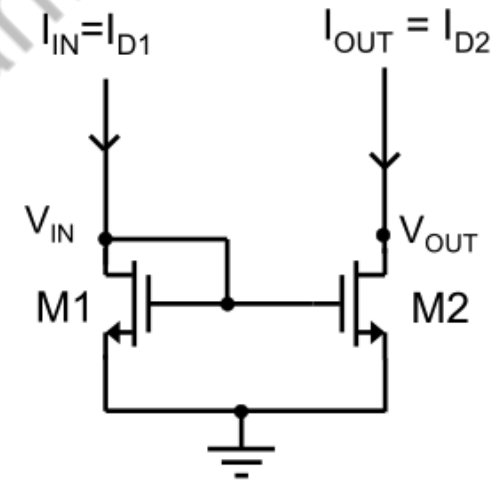
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$$I_{OUT_ideal} = \frac{\left(\frac{W}{L}\right)_2}{\left(\frac{W}{L}\right)_1} I_{IN}$$

Current Mirror Analysis

- This current relationship will be true as long as M2 is in saturation. Clearly, this will happen when $V_O = V_{DS2} > V_{OD2}$
- Gates of two transistors are connected: $V_{GS2} = V_{GS1}$ so $V_{GS2} - V_{TH2} = V_{GS1} - V_{TH1}$ as $V_{TH1} = V_{TH2} \rightarrow V_{OD1} = V_{OD2}$
- Define the minimum output voltage: $V_{Omin} > V_{GS2} - V_{TH2} = V_{OD}$
- Hence it is a benefit to have a low gate overdrive to increase the output swing.
- How much should the gate overdrive be?
- For same drain current, if the overdrive is small, transistor size will be very large, giving area penalty and speed penalty.
- Overdrive voltage is a trade-off between speed and minimum output swing. Typically, overdrive is selected between 0.1-0.4V.

Current Mirror Analysis

A current mirror with current ratio of two is designed. Assume $V_{IN} = V_{OUT}$ to eliminate the channel length modulation effect.

Due to mismatch between M1 and M2, the output current is not exactly two times of the input current.

3 ways to implement:

- A: $W_2 = W_1, L_2 = 0.5L_1$

$$\frac{I_{OUT}}{I_{IN}} = \frac{\left(\frac{W}{L}\right)_2 (1 + \lambda_2 V_{OUT})}{\left(\frac{W}{L}\right)_1 (1 + \lambda_1 V_{IN})} \neq 2$$
 - λ mismatch

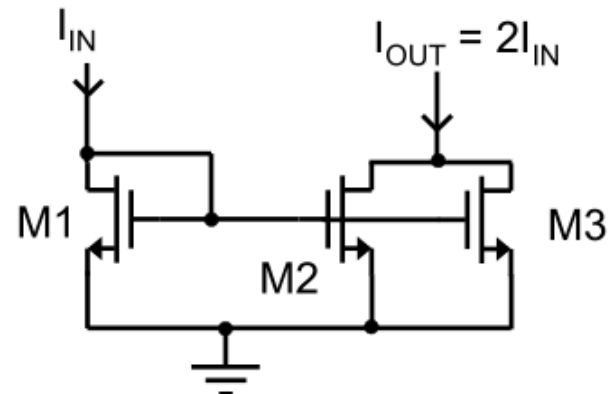
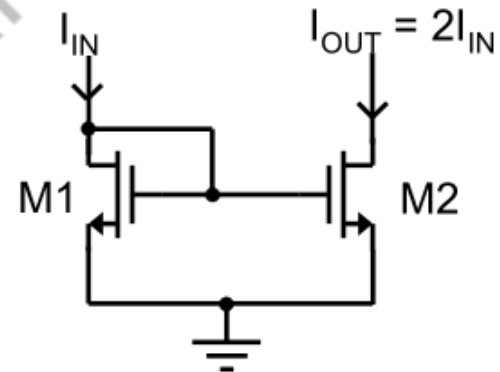
- B: $W_2 = 2W_1, L_2 = L_1$

$$\frac{I_{OUT}}{I_{IN}} = \frac{2W + \Delta W}{\frac{L + \Delta L}{W + \Delta W}} \neq 2$$
 - ΔW and ΔL mismatch

- C: Two transistors in parallel,
 $W_3 = W_2 = W_1, L_3 = L_2 = L_1$

Best solution

$$\frac{I_{OUT}}{I_{IN}} = \frac{2(W + \Delta W)}{\frac{L + \Delta L}{W + \Delta W}} = 2$$



Eliminate the Systematic Error

As we have seen, first simple current mirror output current ($I_{OUT} = I_{D2}$) changes when the drain voltage of M2 changes. From model parameter $\lambda = 0.05$, the change in I_{OUT} for a 1V change in V_{D2} will be 5%, which is not acceptable in many analog applications.

Can we do something about this?

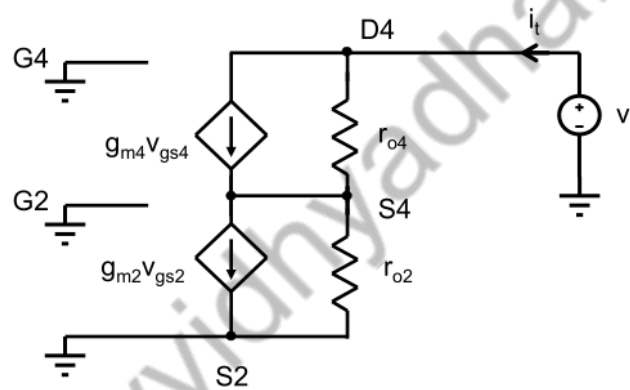
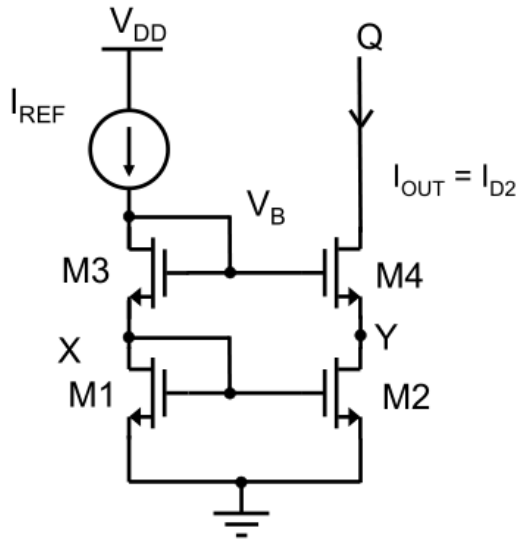
$$E = \frac{I_{OUT} - I_{OUT_ideal}}{I_{OUT_ideal}} = \frac{(1 + \lambda V_{OUT})}{(1 + \lambda V_{IN})} - 1 \approx \lambda(V_{OUT} - V_{IN})$$

The key to eliminate the current gain systematic error is to make $V_{OUT} = V_{IN}$ in the simple current mirror.

A straightforward way to achieve this would be having an extra MOSFET in series with M2 and fix the drain voltage of M2 to V_{IN} . This extra transistor is called cascode transistor.

Standard Cascode Current Mirror

Output Resistance



$$v_{gs2} = 0, v_{gs4} = -i_t r_{o2}$$

$$i_t = \frac{v_t - v_{s4}}{r_{o4}} - g_{m4} i_t r_{o2}$$

$$i_t (1 + g_{m4} r_{o2}) = \frac{v_t - i_t r_{o2}}{r_{o4}}$$

$$R_O = \frac{v_t}{i_t} = r_{o4} (1 + g_{m4} r_{o2}) + r_{o2}$$

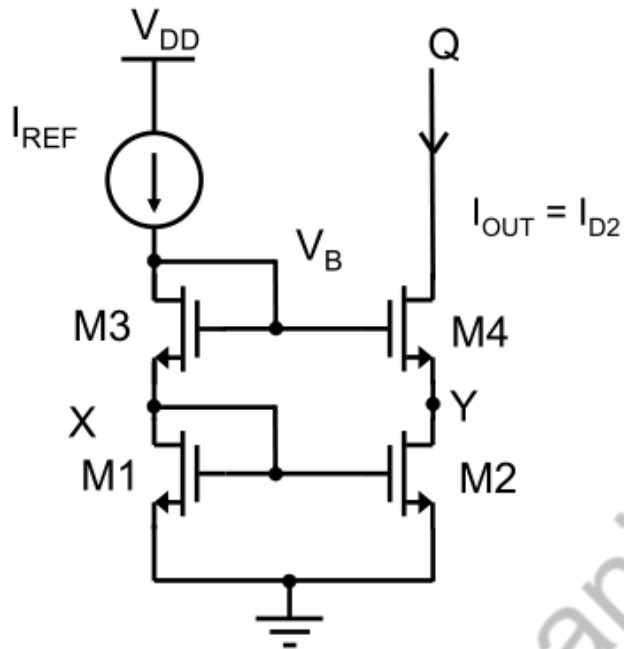
$$R_O = g_{m4} r_{o2}^2$$

If body effect is included: $R_O = (g_{m4} + g_{mb}) r_{o2}^2$

Features of Cascode current mirror:

- No current gain systematic error.
- Higher output resistance.
- Higher minimum output voltage.

Standard Cascode Current Mirror



All 4 MOSFETs have the same V_{TH} if body effect is ignored.

$$V_X = V_Y = V_{TH} + V_{OV}$$

$V_{GS3} = V_{OV} + V_{TH}$ as M1 and M3 carry the same "I"

$V_{G3} = V_{GS3} + V_X = 2V_{TH} + 2V_{OV}$ ignoring body effect.

$$V_{G4} = 2V_{TH} + 2V_{OV}$$

This should also be the case with body effect – only

$2V_{TH}$ will become $V_{TH1} + V_{TH3}$.

$$\text{Min } V_{out} = V_X + V_{OV} = V_{TH} + 2V_{OV}$$