



# **Advanced VLSI Design : 2021-22**

## **Lecture 13**

### **Interconnects**

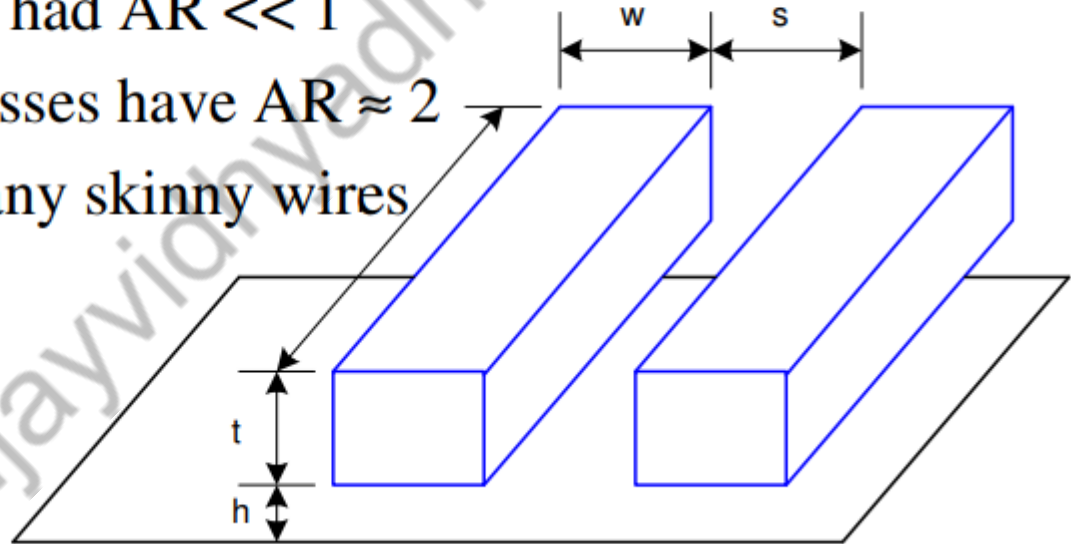
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# Interconnects

- Chips are mostly made of wires called *interconnect*
  - In stick diagram, wires set size
  - Transistors are little things under the wires
  - Many layers of wires
- Wires are as important as transistors
  - Speed
  - Power
  - Noise
  - Area
- Alternating layers run orthogonally

# Wire Geometry

- Pitch =  $w + s$
- Aspect ratio:  $AR = t/w$ 
  - Old processes had  $AR \ll 1$
  - Modern processes have  $AR \approx 2$ 
    - Pack in many skinny wires



# Layer Stack

- AMI 0.6  $\mu\text{m}$  process has 3 metal layers
- Modern processes use 6-10+ metal layers

- Example:

Intel 180 nm process

- M1: thin, narrow ( $< 3\lambda$ )

- High density cells

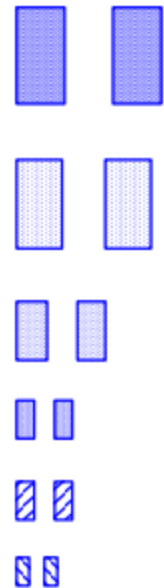
- M2-M4: thicker

- For longer wires

- M5-M6: thickest

- For  $V_{DD}$ , GND, clk

Layer	T (nm)	W (nm)	S (nm)	AR
6	1720	860	860	2.0
	1000			
5	1600	800	800	2.0
	1000			
4	1080	540	540	2.0
	700			
3	700	320	320	2.2
	700			
2	700	320	320	2.2
	700			
1	480	250	250	1.9
	800			



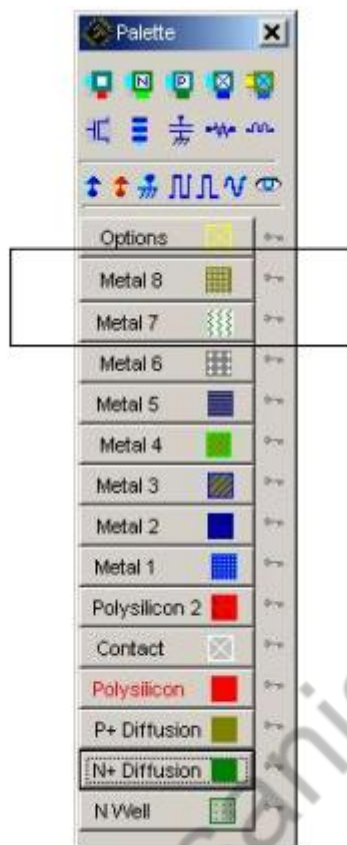
# Choice of Metals

- Until the 180 nm generation, most wires were aluminum
- Modern processes often use copper
  - Cu atoms diffuse into silicon and damage FETs
  - Must be surrounded by a diffusion barrier

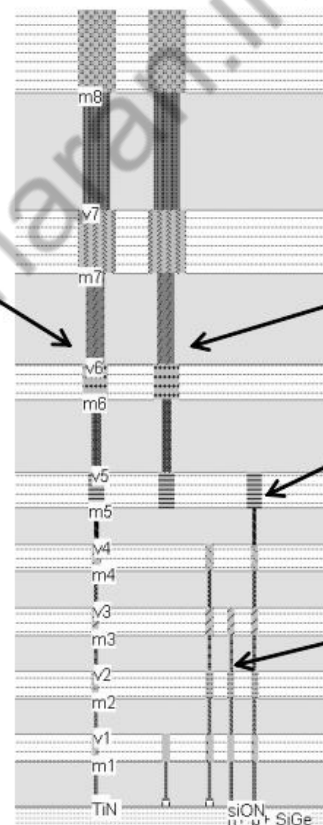
Metal	Bulk Resistivity ( $\mu\Omega * cm$ )
Silver (Ag)	1.6
Copper (Cu)	1.7
Gold (Au)	2.2
Aluminum (Al)	2.8
Tungsten (W)	5.3
Molybdenum (Mo)	5.3

# Metal Layers 45 nm Technology

New layers introduced in 65-nm technology node



Contact poly-metal1-  
..-metal8



Contact  
Metal5..metal8

Contact  
P+diff/metal1..metal5

Contact  
poly/metal1..metal3

# Wire Resistance

$\rho = \text{resistivity } (\Omega \cdot \text{m})$

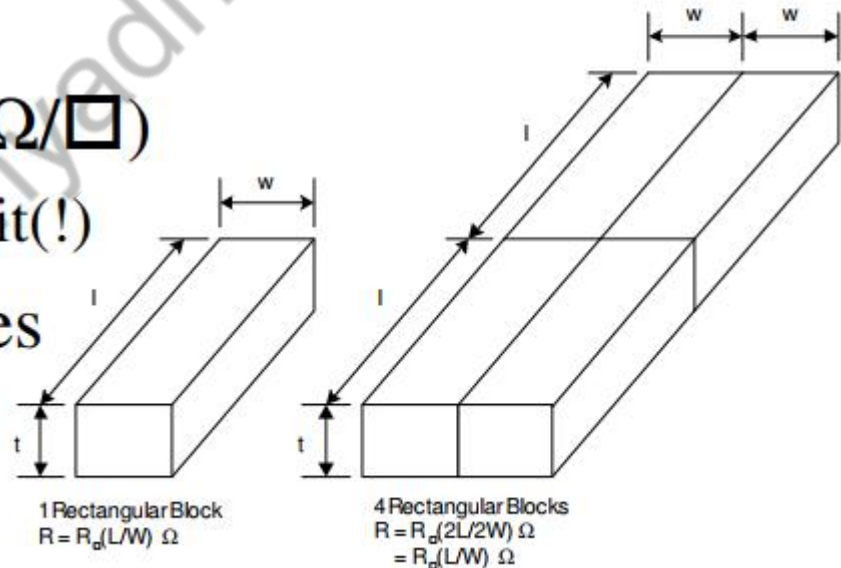
$$R = \frac{\rho}{t} \frac{l}{w} = R_{\square} \frac{l}{w}$$

- $R_{\square} = \text{sheet resistance } (\Omega/\square)$

- $\square$  is a dimensionless unit(!)

- Count number of squares

- $R = R_{\square} * (\# \text{ of squares})$



# Sheet Resistance

Typical sheet resistances in 180 nm process

Layer	Sheet Resistance ( $\Omega/\square$ )
Diffusion (silicided)	3–10
Diffusion (no silicide)	50–200
Polysilicon (silicided)	3–10
Polysilicon (no silicide)	50–400
Metal1	0.08
Metal2	0.05
Metal3	0.05
Metal4	0.03
Metal5	0.02
Metal6	0.02



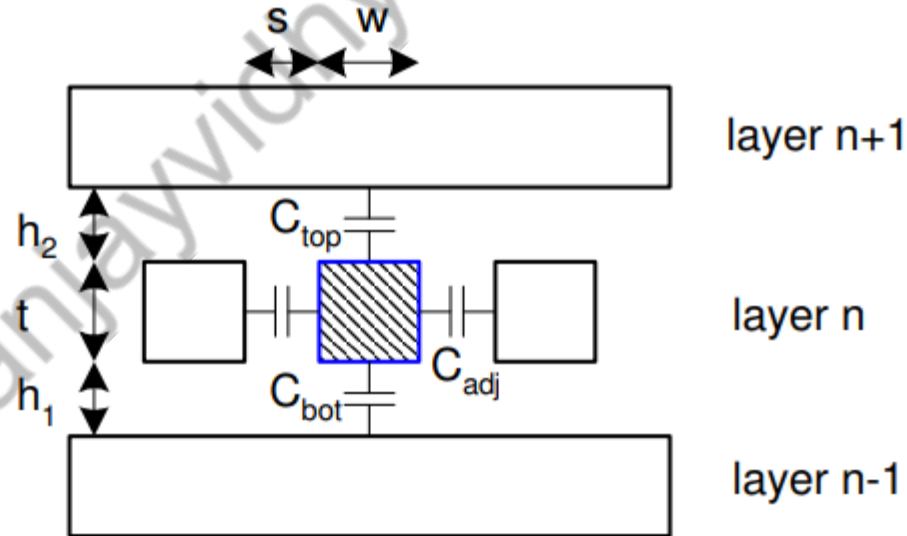
# Contacts Resistance

- Contacts and vias also have 2-20  $\Omega$
- Use many contacts for lower R
  - Many small contacts for current crowding around periphery



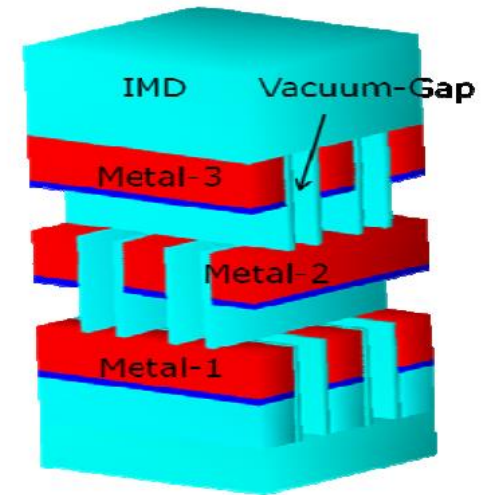
# Wire Capacitance

- Wire has capacitance per unit length
  - To neighbors
  - To layers above and below
- $C_{\text{total}} = C_{\text{top}} + C_{\text{bot}} + 2C_{\text{adj}}$

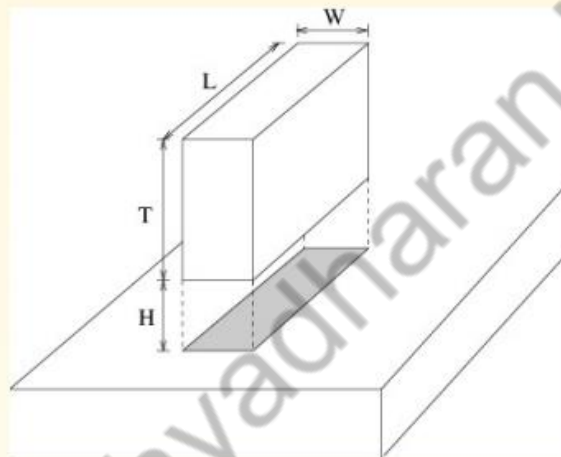


# Capacitance Trends

- Parallel plate equation:  $C = \epsilon A/d$ 
  - Wires are not parallel plates, but obey trends
  - Increasing area (W, t) increases capacitance
  - Increasing distance (s, h) decreases capacitance
- Dielectric constant
  - $\epsilon = k\epsilon_0$
- $\epsilon_0 = 8.85 \times 10^{-14} \text{ F/cm}$
- $k = 3.9$  for  $\text{SiO}_2$
- Processes are starting to use low-k dielectrics
  - $k \approx 3$  (or less) as dielectrics use air pockets
- Typical (M2) wires have  $\sim 0.2 \text{ fF}/\mu\text{m}$ 
  - Compare to  $2 \text{ fF}/\mu\text{m}$  for gate capacitance

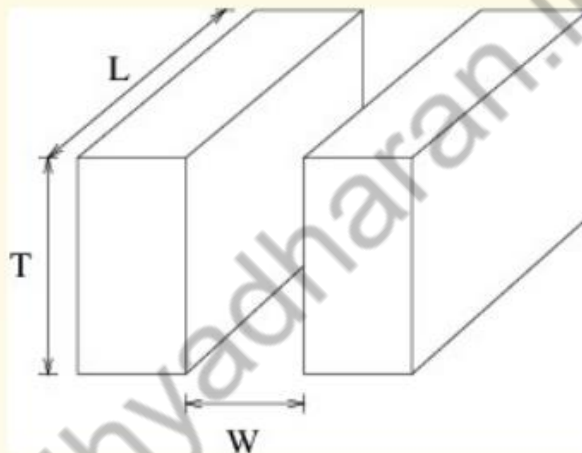


# Capacitance Trends



- $W \gg H \Rightarrow$  Parallel Plate Model
  - $C = k \cdot \epsilon_0 \cdot \frac{W \cdot L}{H}$
- $W \leq H \Rightarrow$  Fringing Model
  - $C \propto \log(W)$
- For Deep Sub-Micron (DSM) (or nanoscale) processes, fringing model applies

# Capacitance Trends



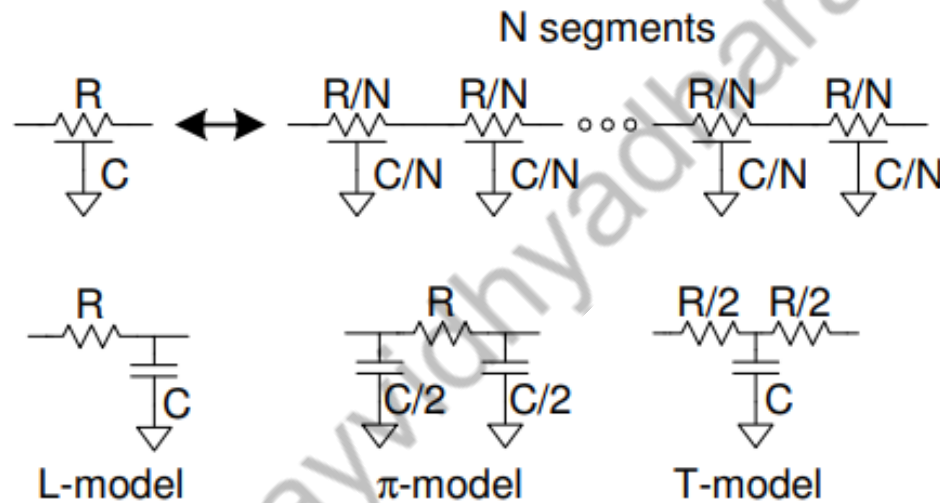
- $T \gg W \Rightarrow$  Parallel Plate Model
  - $C = k \cdot \epsilon_0 \cdot \frac{T \cdot L}{W}$
- $T \leq W \Rightarrow$  Fringing Model
  - $C \propto \log(T)$
- For DSM processes, parallel plate model applies

# Polysilicon

- Diffusion capacitance is very high (about 2 fF/ $\mu\text{m}$ )
  - Comparable to gate capacitance
  - Diffusion also has high resistance
  - Avoid using diffusion *runners* for wires!
- Polysilicon has lower C but high R
  - Use for transistor gates
  - Occasionally for very short wires between gates

# Lumped Element Models

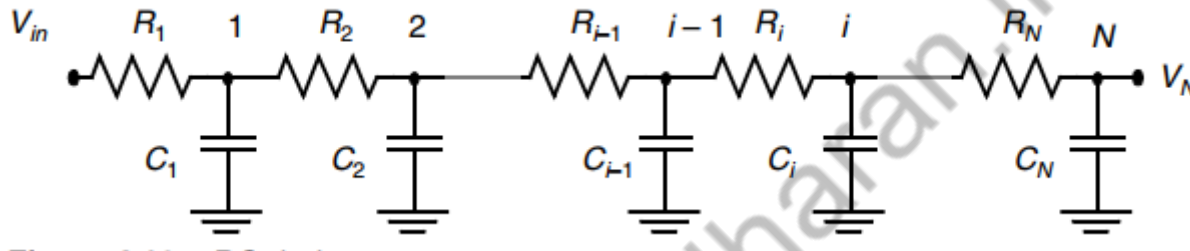
- Wires are a distributed system
  - Approximate with lumped element models



- 3-segment  $\pi$ -model is accurate to 3% in simulation

# Lumped Element Models

## L Model



$$\tau_{Di} = C_1 R_1 + C_2 (R_1 + R_2) + \dots + C_i (R_1 + R_2 + \dots + R_i)$$

The wire with a total length of  $L$  is partitioned into  $N$  identical segments, each with a length of  $L/N$ . The resistance and capacitance of each segment are hence given by  $rL/N$  and  $cL/N$ , respectively.

$$\tau_{DN} = \left(\frac{L}{N}\right)^2 (rc + 2rc + \dots + Nrc) = (rcL^2) \frac{N(N+1)}{2N^2} = RC \frac{N+1}{2N}$$

$$\tau_{DN} = \frac{RC}{2} = \frac{rcL^2}{2}$$

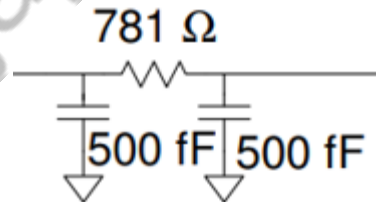
The delay of a wire is **a quadratic function of its length!** This means that doubling the length of the wire quadruples its delay



# Lumped Element Models

## Example

- Metal2 wire in 180 nm process
  - 5 mm long
  - $0.32\text{ }\mu\text{m}$  wide
  - Number of squares =  $5000/0.32 = 15625$
- Construct a 3-segment  $\pi$ -model
  - $R_{\square} = 0.05\text{ }\Omega/\square \Rightarrow R = 15625 * 0.05 = 781\text{ }\Omega$
  - $C_{\text{permicron}} = 0.2\text{ fF}/\mu\text{m} \Rightarrow C = 0.2\text{ fF}/\mu\text{m} * 5000\text{ }\mu\text{m} = 1\text{ pF}$

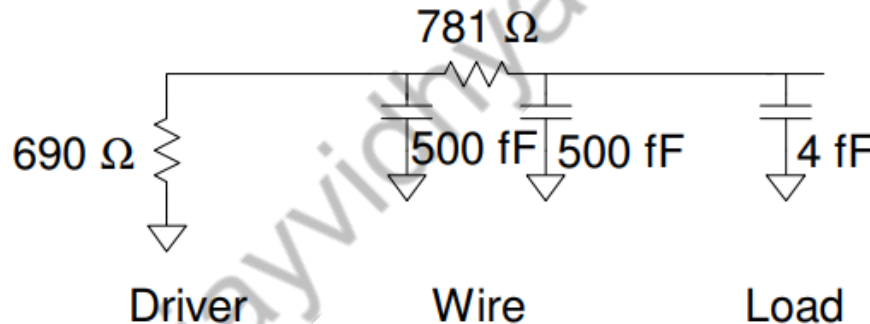


# Lumped Element Models

- Estimate the delay of a 10x inverter driving a 2x inverter at the end of the 5mm wire from the previous example.
  - $R = 2.5 \text{ k}\Omega \cdot \mu\text{m}$  for gates
  - Unit inverter:  $0.36 \mu\text{m}$  nMOS,  $0.72 \mu\text{m}$  pMOS
  - Unit inverter has  $4\lambda = 0.36 \mu\text{m}$  wide nMOS,  $8\lambda = 0.72 \mu\text{m}$  wide pMOS
  - Unit inverter: effective resistance of  $(2.5 \text{ k}\Omega \cdot \mu\text{m}) / (0.36 \mu\text{m}) = 6.9 \text{ k}\Omega$
  - Capacitance:  $(0.36 \mu\text{m} + 0.72 \mu\text{m}) * (2 \text{ fF}/\mu\text{m}) = 2 \text{ fF}$

## Elmore delay model

- $t_{pd} = 1.1 \text{ ns}$



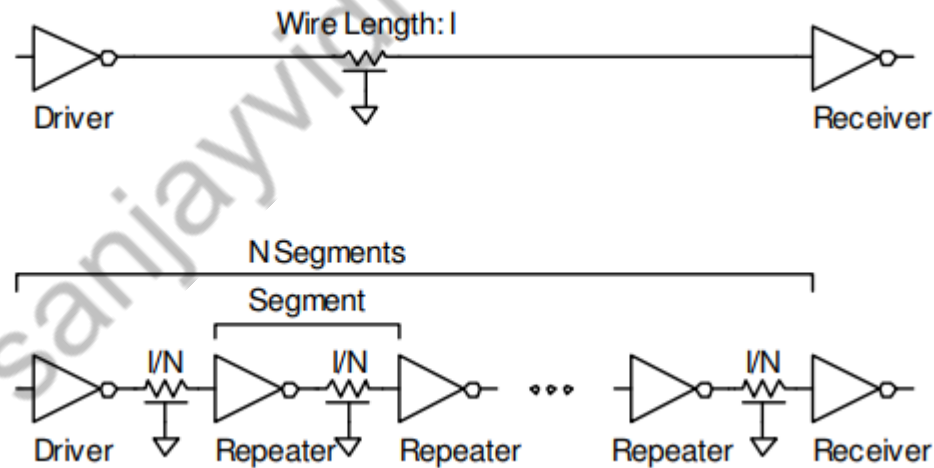
Empirical values have been found for  $R_N$  and  $R_P$ ,

$$R_N = \frac{12.5}{(W/L)_n} \text{ k}\Omega$$

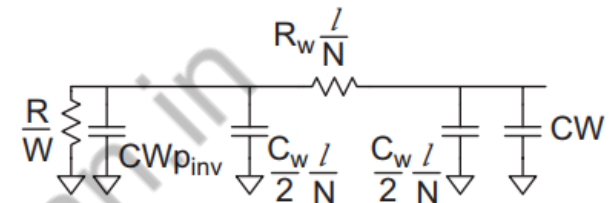
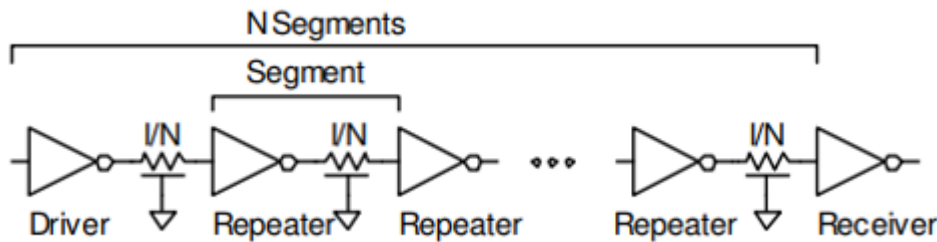
$$R_P = \frac{30}{(W/L)_p} \text{ k}\Omega$$

# Repeaters

- R and C are proportional to  $l$
- RC delay is proportional to  $l^2$ 
  - Unacceptably great for long wires
- Break long wires into N shorter segments
  - Drive each one with an inverter or buffer



# Repeaters



$$t_{pd} = N \left[ \frac{R}{W} \left( C_w \frac{l}{N} + CW(1 + p_{inv}) \right) + R_w \frac{l}{N} \left( \frac{C_w l}{2N} + CW \right) \right]$$

$$\frac{l}{N} = \sqrt{\frac{2RC(1 + p_{inv})}{R_w C_w}}$$

FO4 inverter is  $5RC$ . Assuming  $p_{inv} \approx 0.5$

$$\frac{l}{N} = 0.77 \sqrt{\frac{FO4}{R_w C_w}}$$

The delay per unit length of a properly repeated wire is

$$\frac{t_{pd}}{l} = \left( 2 + \sqrt{2(1 + p_{inv})} \right) \sqrt{RCR_w C_w} \approx 1.67 \sqrt{FO4 R_w C_w}$$

To achieve this delay, the inverters should use an nMOS transistor width of

$$W = \sqrt{\frac{RC_w}{R_w C}}$$

# Crosstalk

A capacitor does not like to change its voltage instantaneously

A wire has high capacitance to its neighbor

When the neighbor switches from  $1 \rightarrow 0$  or  $0 \rightarrow 1$ , the wire tends to switch too Called capacitive **coupling** or **crosstalk**

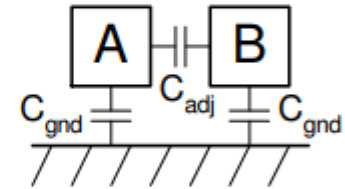
Crosstalk effects

**Noise** on nonswitching wires

Increased **delay** on switching wires

# Crosstalk Delay

- Assume layers above and below on average are quiet
  - Second terminal of capacitor can be ignored
  - Model as  $C_{\text{gnd}} = C_{\text{top}} + C_{\text{bot}}$
- Effective  $C_{\text{adj}}$  depends on behavior of neighbors
  - Miller effect*

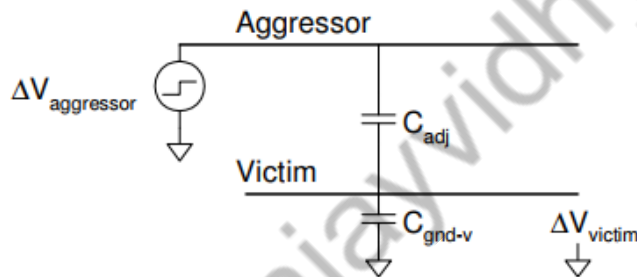


B	$\Delta V$	$C_{\text{eff(A)}}$	MCF
Constant	$V_{\text{DD}}$	$C_{\text{gnd}} + C_{\text{adj}}$	1
Switching with A	0	$C_{\text{gnd}}$	0
Switching opposite A	$2V_{\text{DD}}$	$C_{\text{gnd}} + 2 C_{\text{adj}}$	2

# Crosstalk

- Crosstalk causes noise on non-switching wires
- If victim is floating:
  - model as capacitive voltage divider

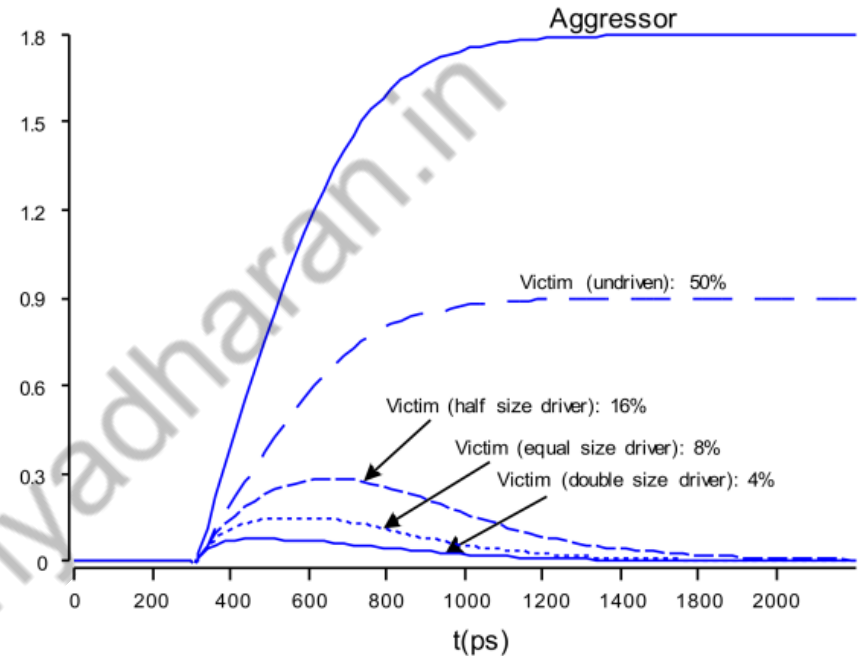
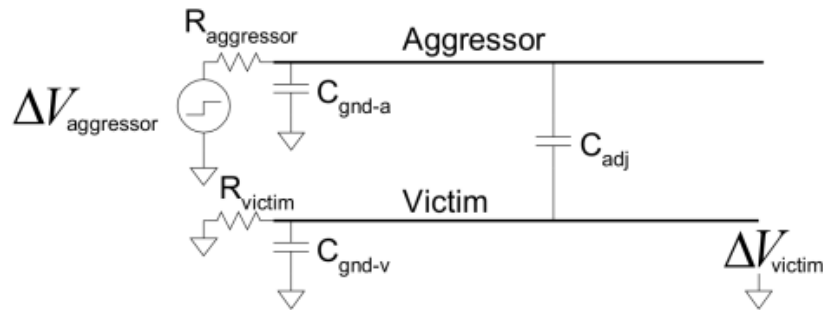
$$\Delta V_{victim} = \frac{C_{adj}}{C_{gnd-v} + C_{adj}} \Delta V_{aggressor}$$



$$C_{adj} (\Delta V_{agg} - \Delta V_{vic}) = C_{gnd} (\Delta V_{vic})$$

# Crosstalk

## Driven Victims



If the noise is less than the noise margin, nothing happens. Static CMOS logic will eventually settle to correct output even if disturbed by large noise spikes.

But glitches cause extra delay, also cause extra power from false transitions.

Dynamic logic never recovers from glitches.

Memories and other sensitive circuits also can produce the wrong answer.





**Thank you**

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